



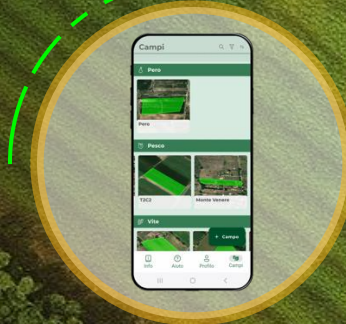
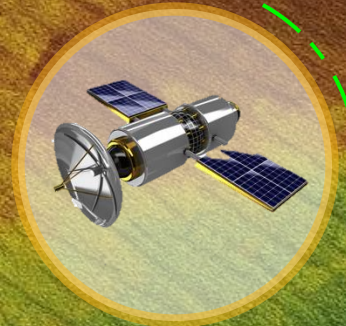
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DECEMBER 9-10, 2025

## Integrating Cutting-Edge Technologies for Crop Monitoring and Management

**Marcelo Barbosa**

Post-Doctoral Associate  
marcelojragro@gmail.com  
University of Georgia





# Integrating Cutting-Edge Technologies for Crop Monitoring and Management



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**Bachelor in Agronomy**  
*Irriga Group*  
Federal University of Alagoas  
Arapiraca Campus

[2014 – 2019]



**Master's Degree in Agronomy**  
*Machinery and Mechanization Lab*  
São Paulo State University  
Jaboticabal Campus

[2019 – 2021]



**PhD in Agronomy**  
*Machinery and Mechanization Lab*  
São Paulo State University  
Jaboticabal Campus

[2021 – 2024]



**Research Assistant**  
*Precision Agriculture Team*  
Louisiana State University  
Baton Rouge Campus

[2022 – 2023]



**GEORGIA**

**Post-Doctoral Associate**  
*Precision Horticulture Lab*  
University of Georgia  
Tifton Campus

[2024 – 2025]



**Assistant Research Professor &  
State Extension Specialist for PA**  
University of Missouri  
FD-REEC

[Start in January 2026]

# Integrating Cutting-Edge Technologies for Crop Monitoring and Management



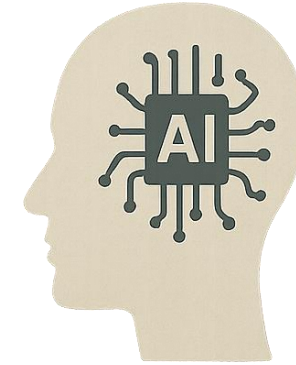
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**Imaging drones**



**Satellite**



**AI**



**Ag Robots**



**Spraying drones**

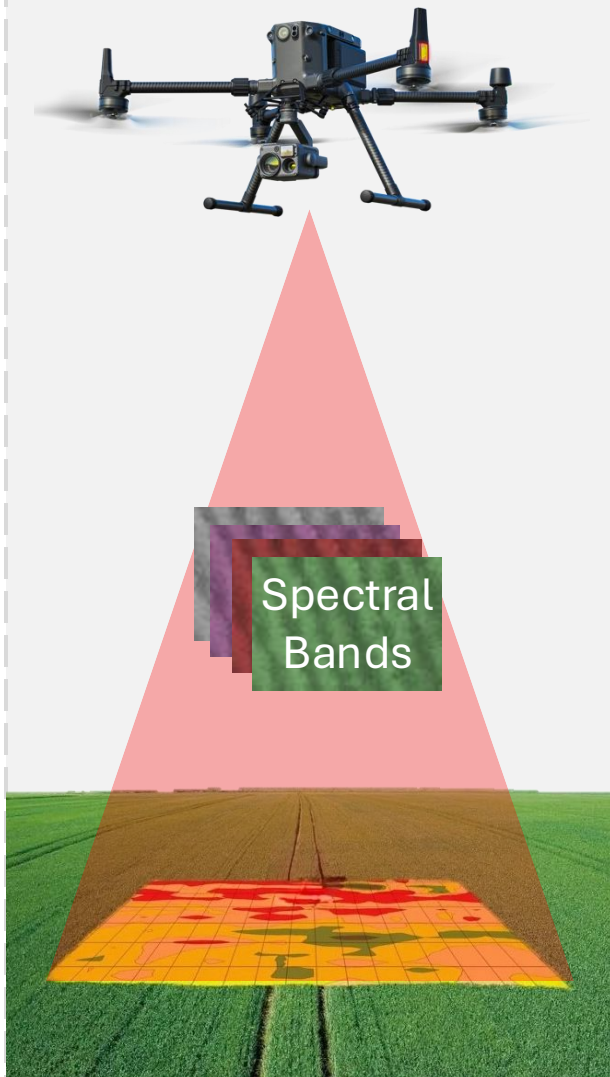


# Integrating Cutting-Edge Technologies for Crop Monitoring and Management

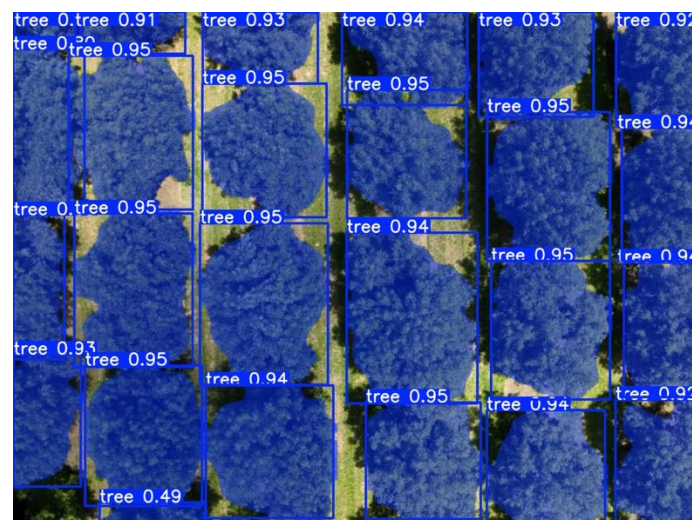
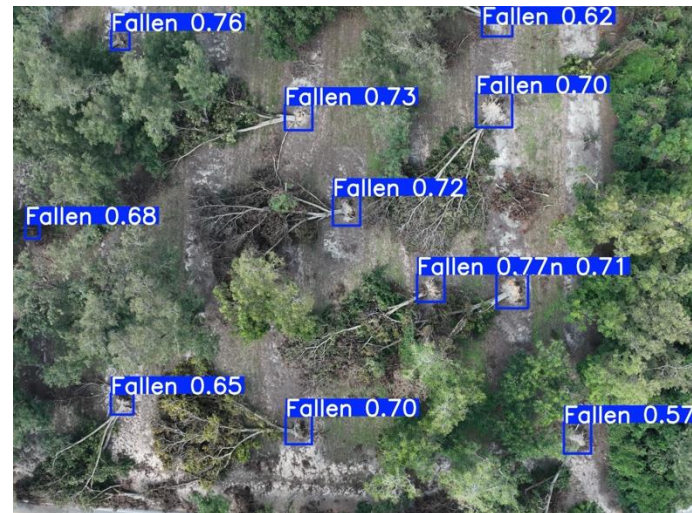


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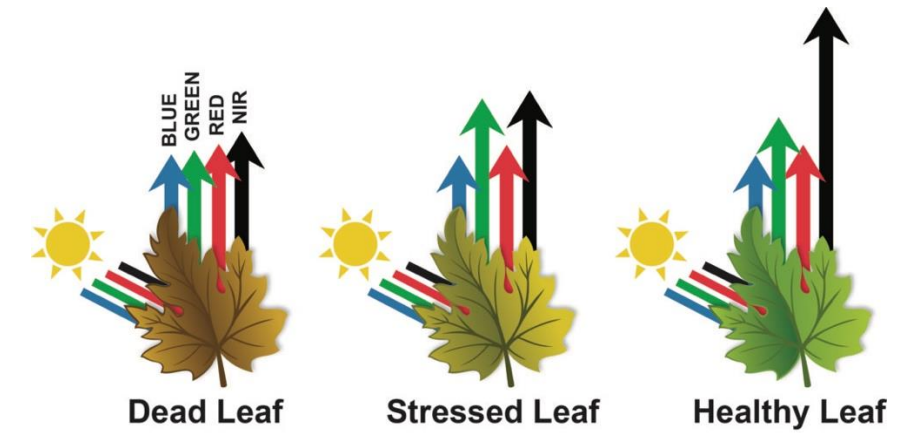
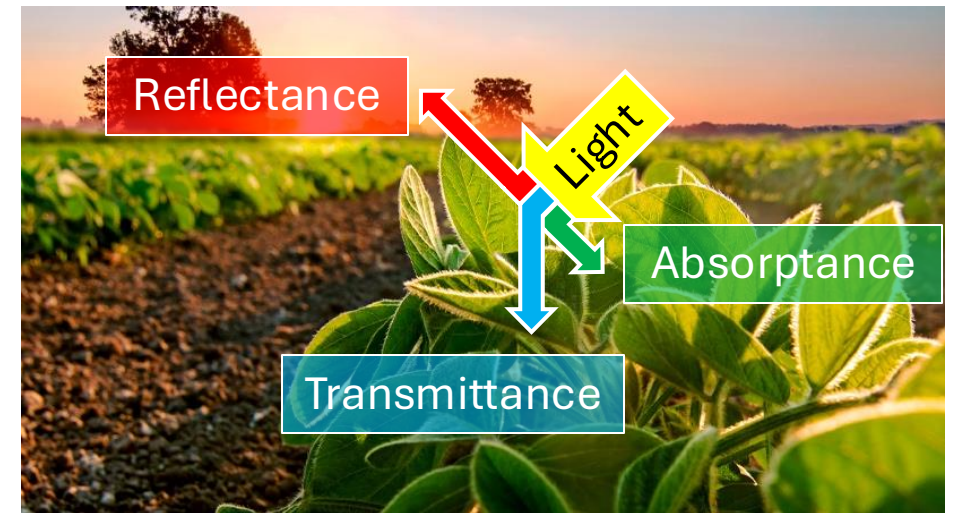
## Drone application



## Object detection/measurement



## Spectral response



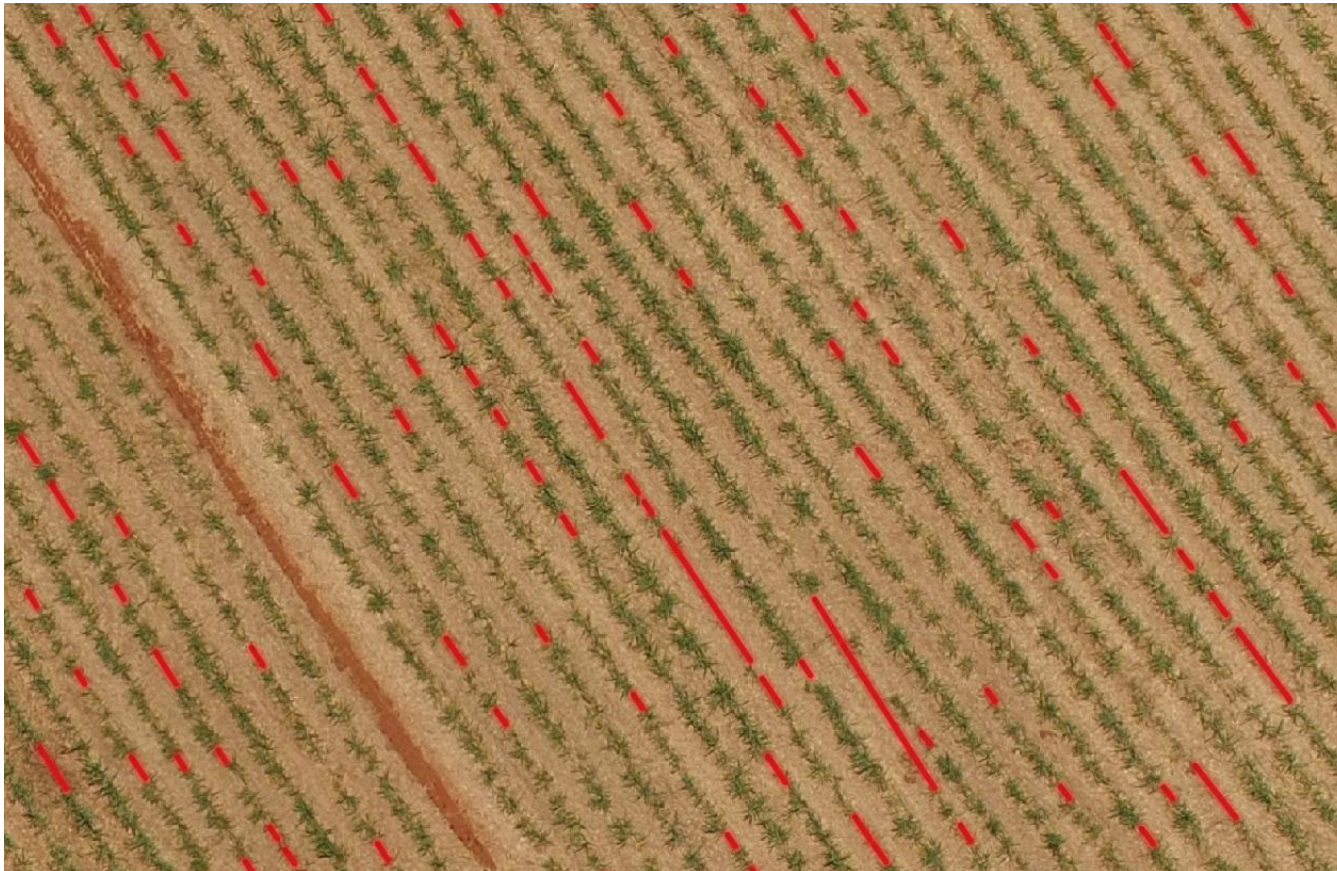
$$NDVI = \frac{NIR - Red}{NIR + Red}$$

The closer to 1, the healthier.





## Mapping Gaps in Sugarcane by UAV RGB Imagery: The Lower and Earlier the Flight, the More Accurate



### Research questions

- Can I detect all the gap lengths through drone images?
- How high should I fly the drone?
- How late in the season should I fly the drone?
- How accurate the measurements are?



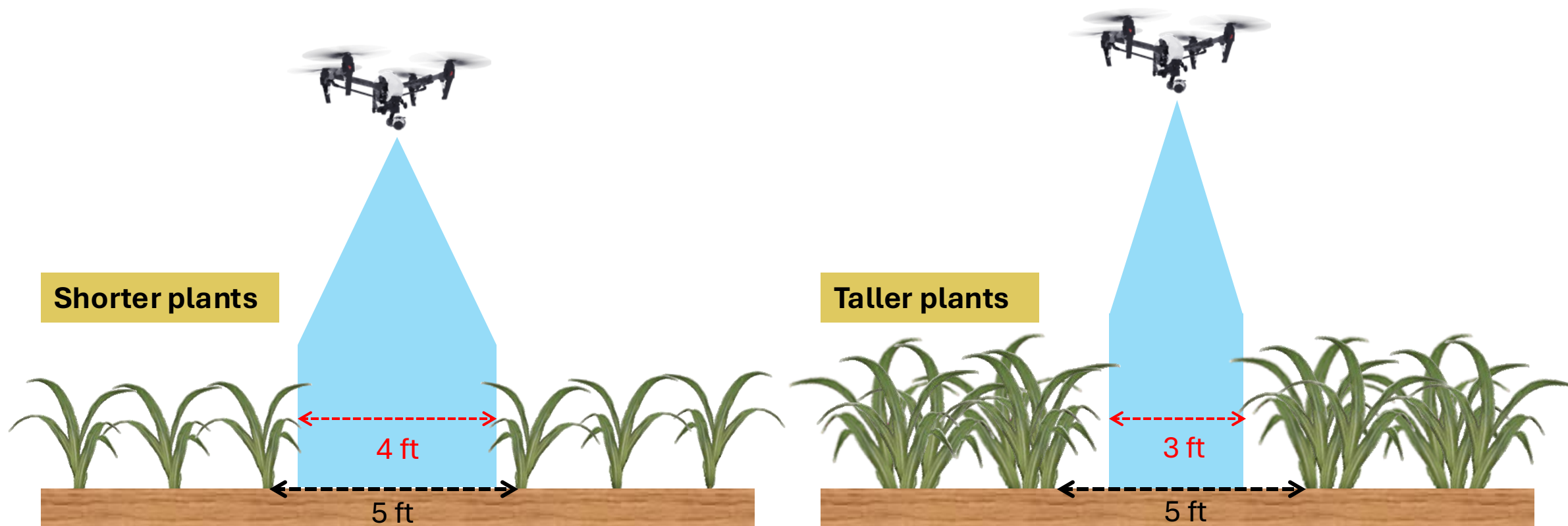
# Integrating Cutting-Edge Technologies for Crop Monitoring and Management



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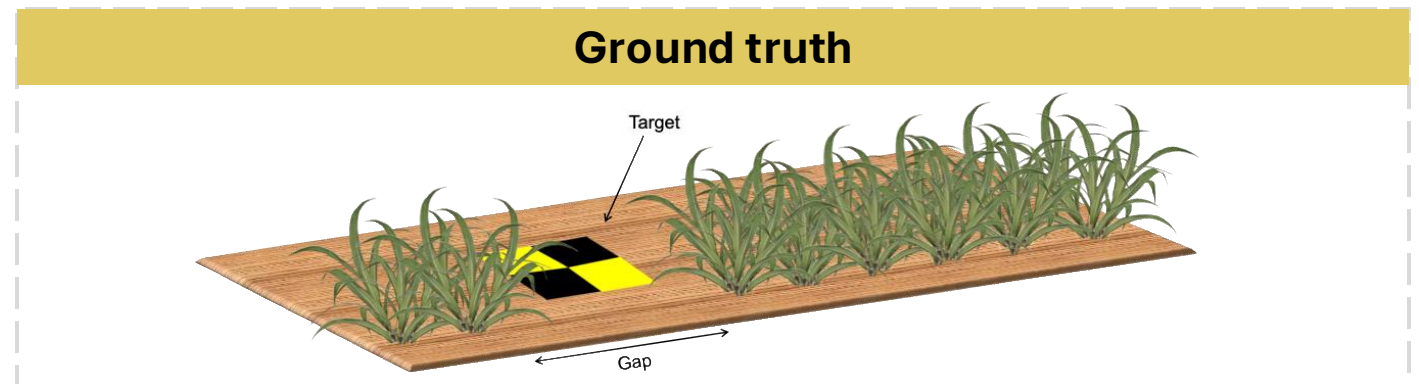
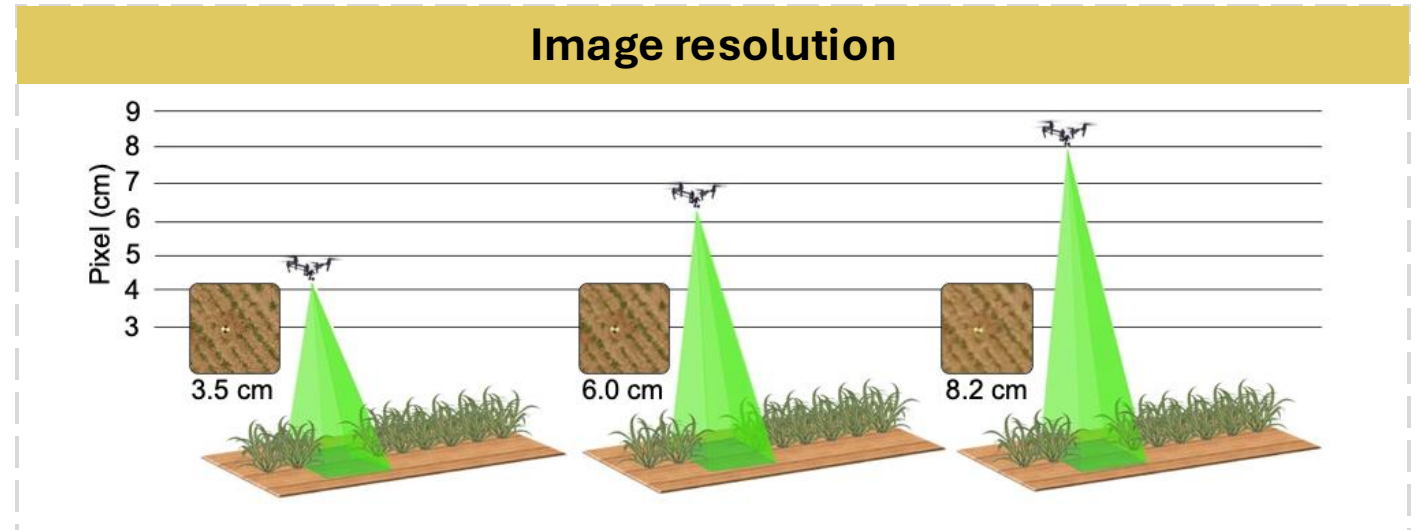
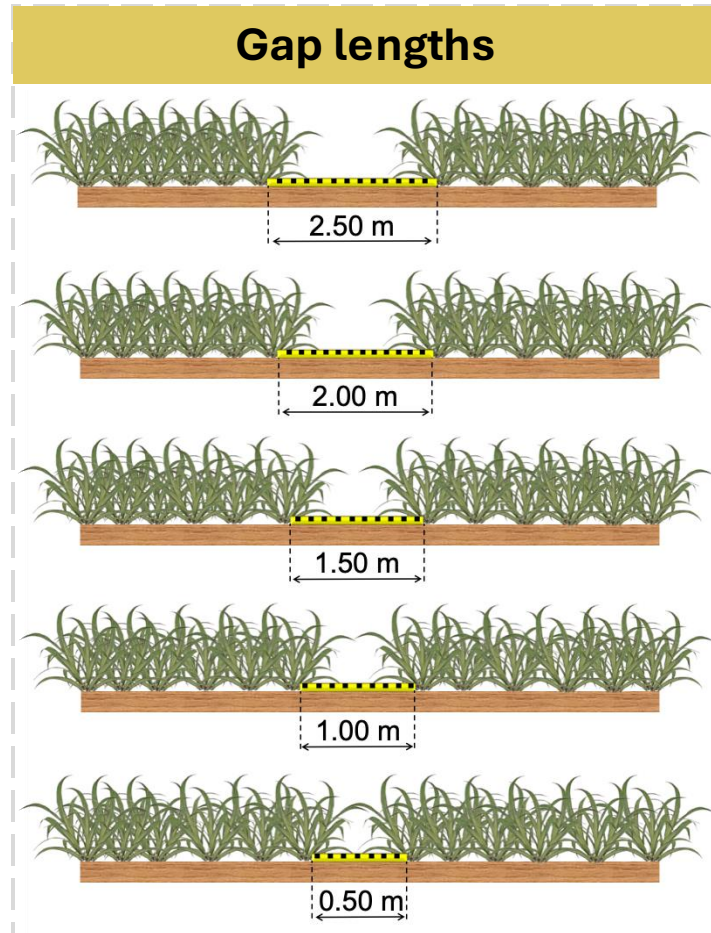
## Mapping Gaps in Sugarcane by UAV RGB Imagery: The Lower and Earlier the Flight, the More Accurate







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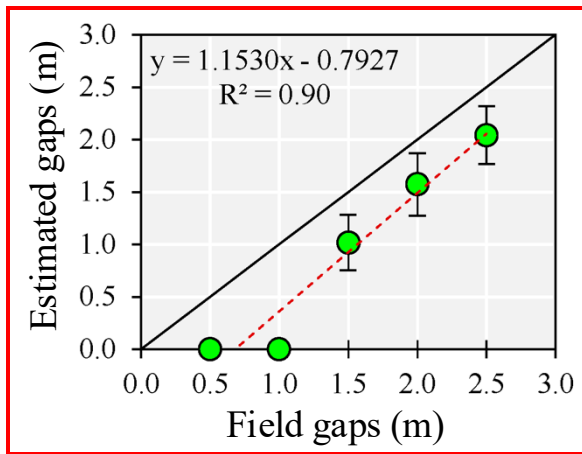
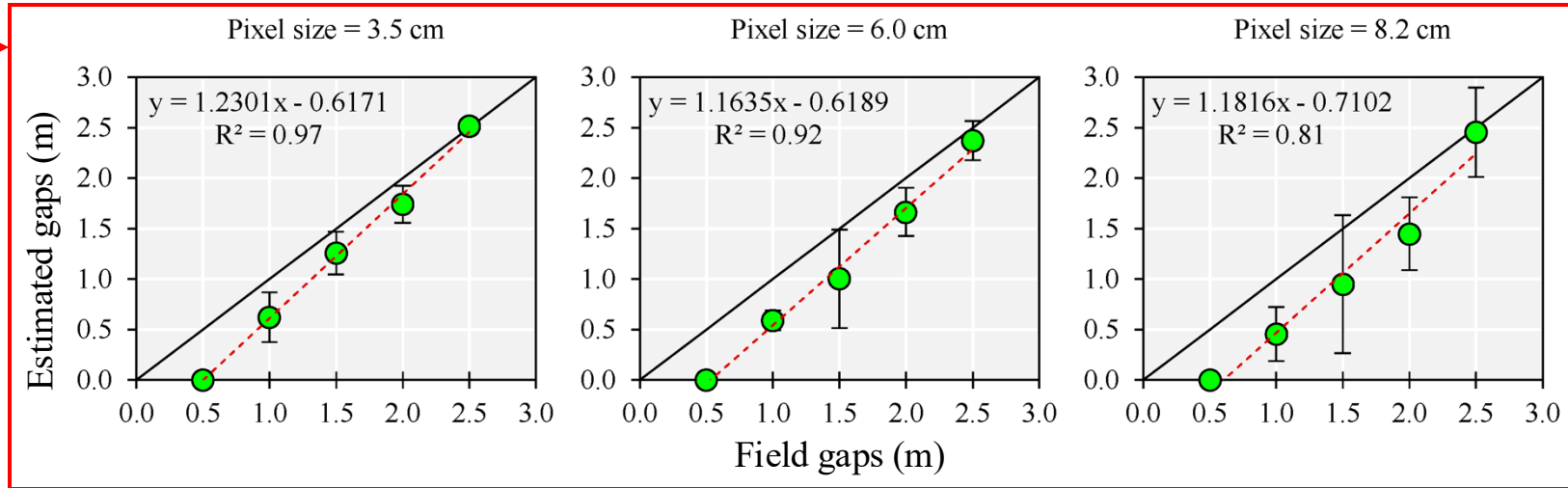
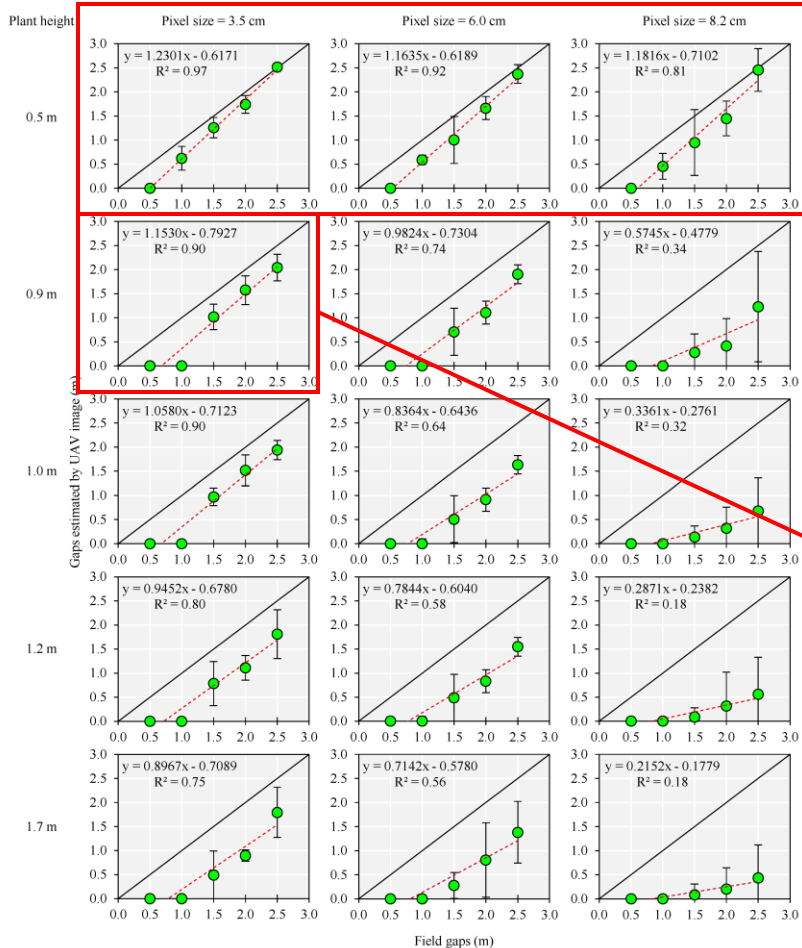
# Integrating Cutting-Edge Technologies for Crop Monitoring and Management



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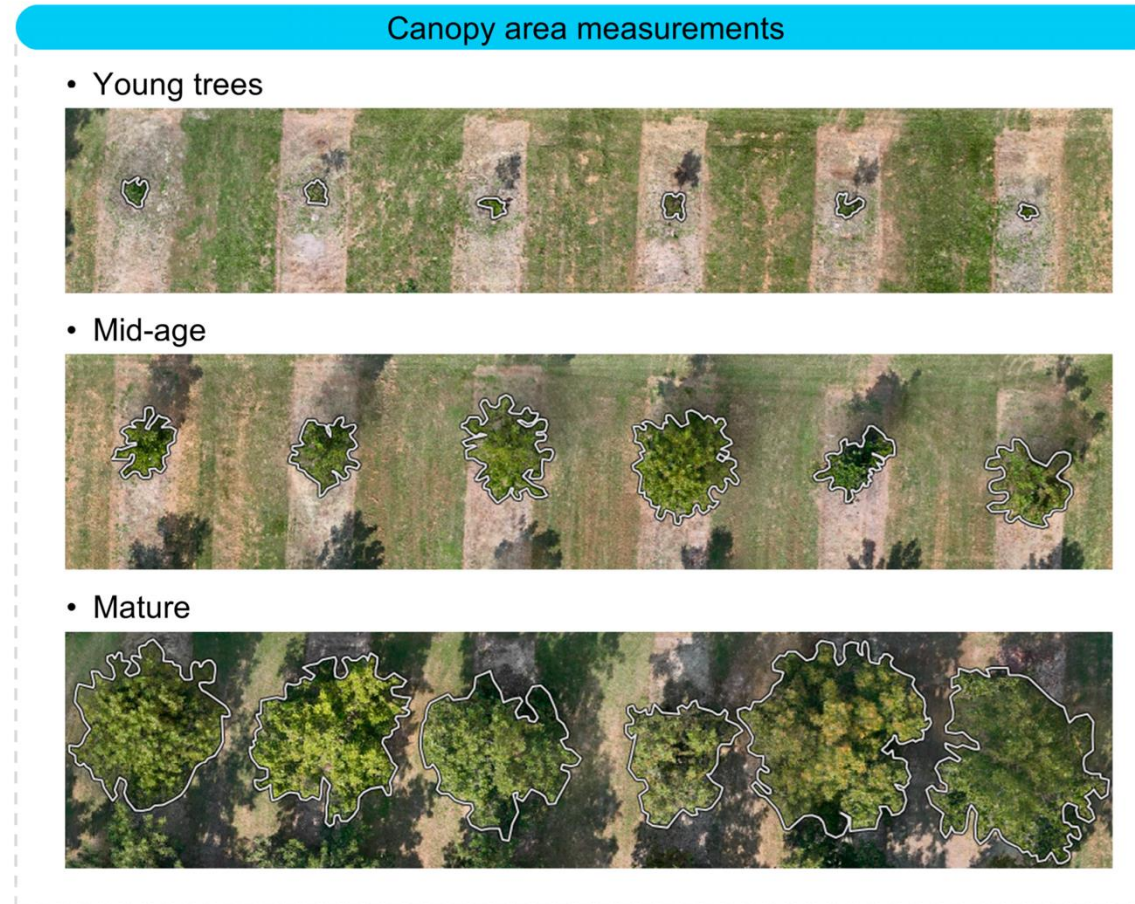
## Mapping Gaps in Sugarcane by UAV RGB Imagery: The Lower and Earlier the Flight, the More Accurate



- Gaps > 1 m (3.28 ft) in length were detected.
- Image resolution should be < 6.0 cm/pixel.
- We should fly when plants are max 0.9 m (~3 ft) tall.
- Measurements were 97% precise and 81% accurate.



## Automated Crop Measurements with UAVs: Evaluation of an AI-Driven Platform for Counting and Biometric Analysis





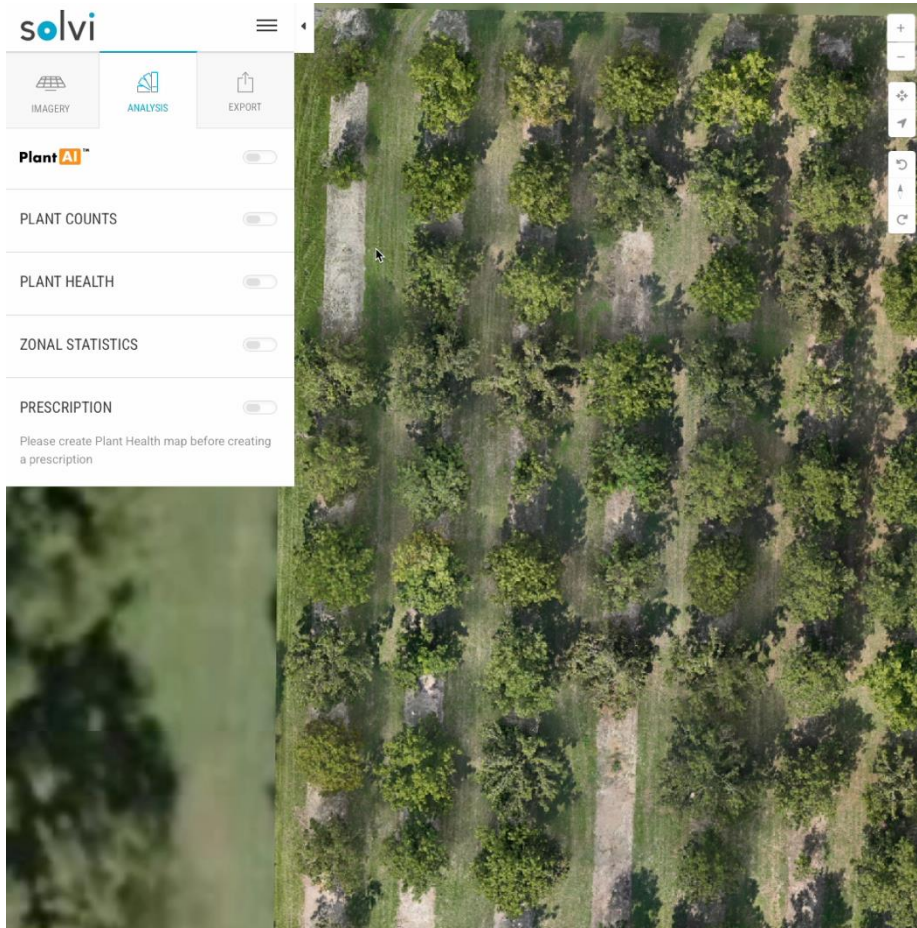
# Integrating Cutting-Edge Technologies for Crop Monitoring and Management



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## Automated Crop Measurements with UAVs: Evaluation of an AI-Driven Platform for Counting and Biometric Analysis







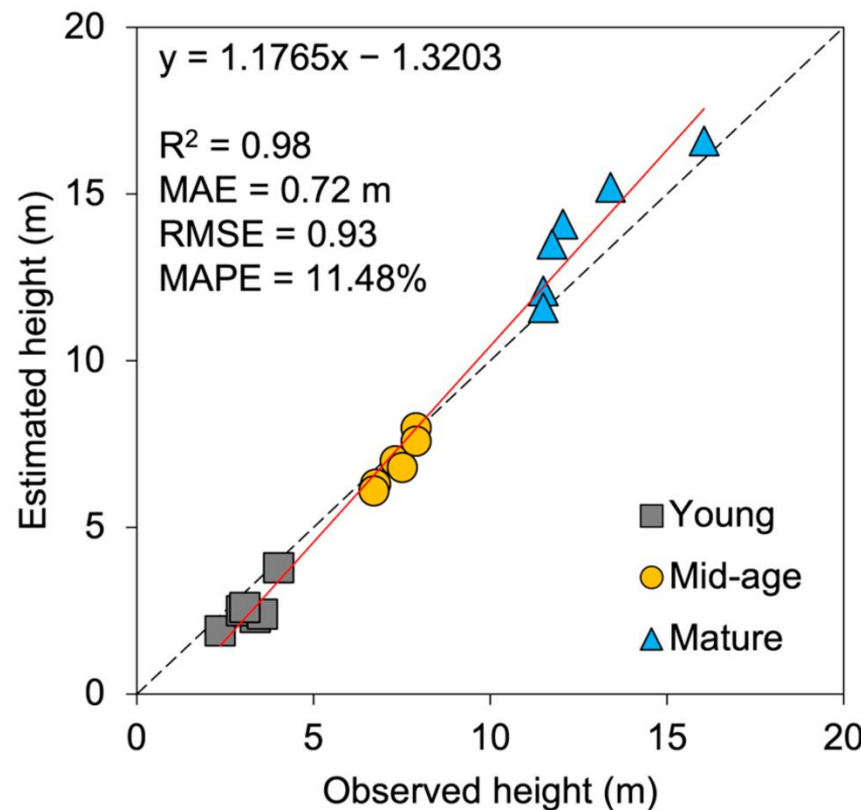
## Automated Crop Measurements with UAVs: Evaluation of an AI-Driven Platform for Counting and Biometric Analysis

### Plant count

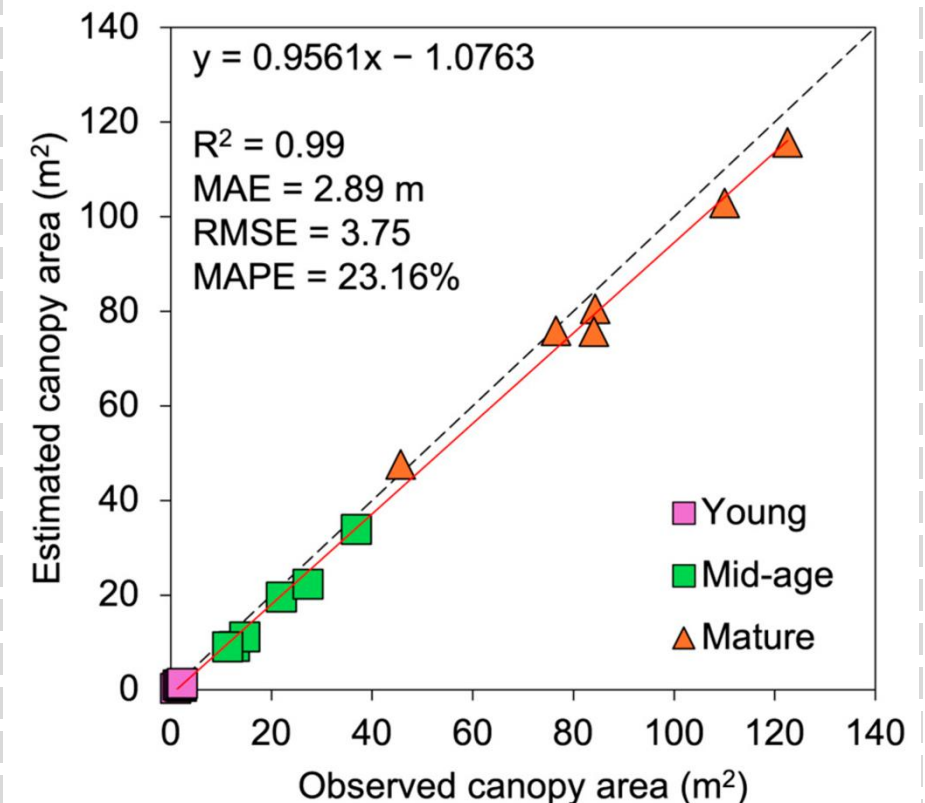
Metric	Value
Precision	0.988
Recall	0.992
F1 Score	0.990

> 99%

### Plant height



### Canopy area





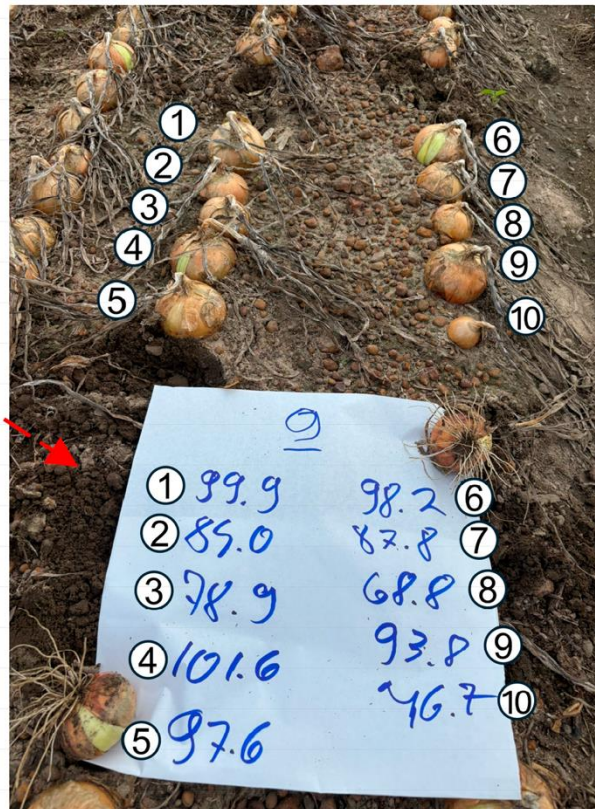


### Automated Crop Measurements with UAVs: Evaluation of an AI-Driven Platform for Counting and Biometric Analysis

Orthomosaic



Sample point (ID 9)



Data classification

ID	Diameter (mm)	Class
1	99.9	Colossal
2	85.0	Jumbo
3	78.9	Jumbo
4	101.6	Colossal
5	97.6	Colossal
6	98.2	Colossal
7	87.8	Jumbo
8	68.8	Medium
9	93.8	Jumbo
10	46.7	Medium

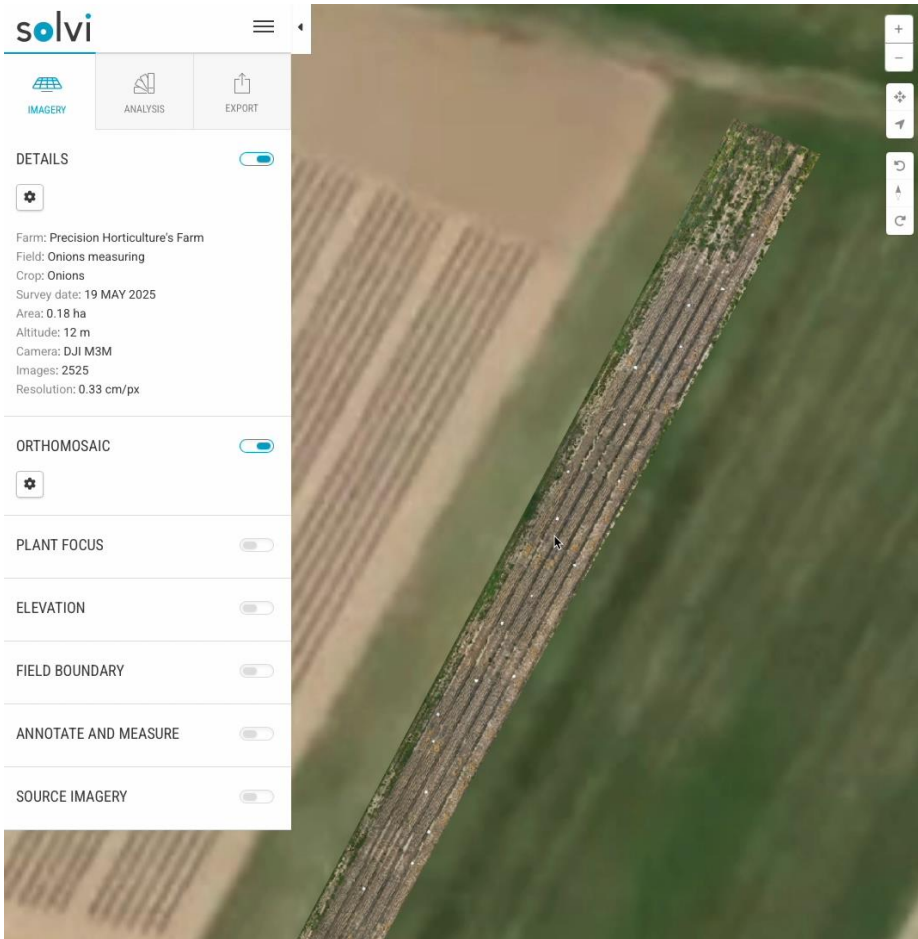


# Integrating Cutting-Edge Technologies for Crop Monitoring and Management



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## Automated Crop Measurements with UAVs: Evaluation of an AI-Driven Platform for Counting and Biometric Analysis







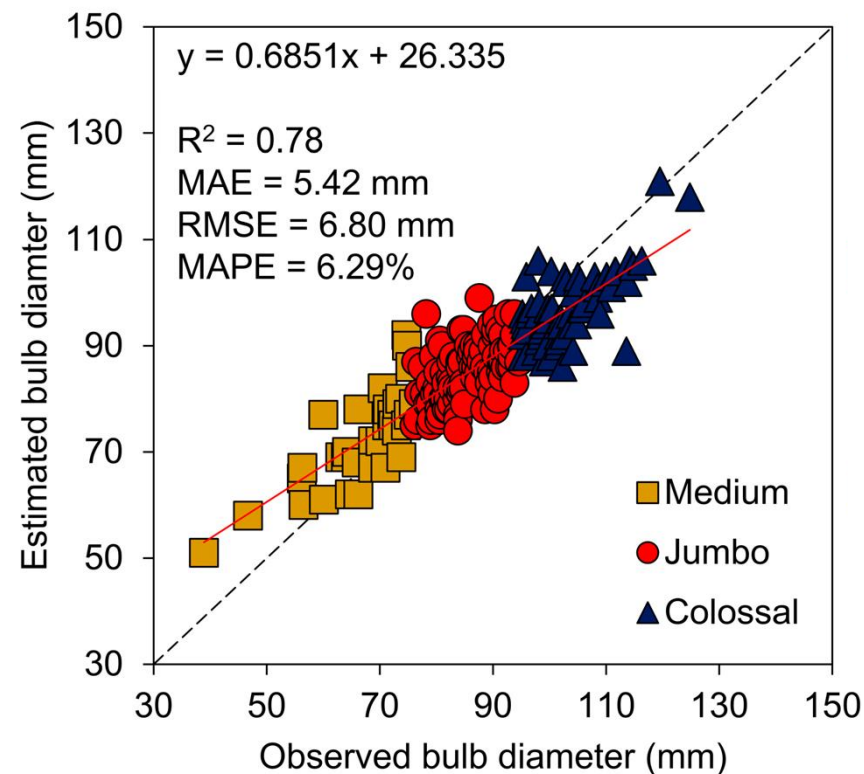
## Automated Crop Measurements with UAVs: Evaluation of an AI-Driven Platform for Counting and Biometric Analysis

### Bulb count

Metric	Value
Precision	0.985
Recall	0.970
F1 Score	0.978

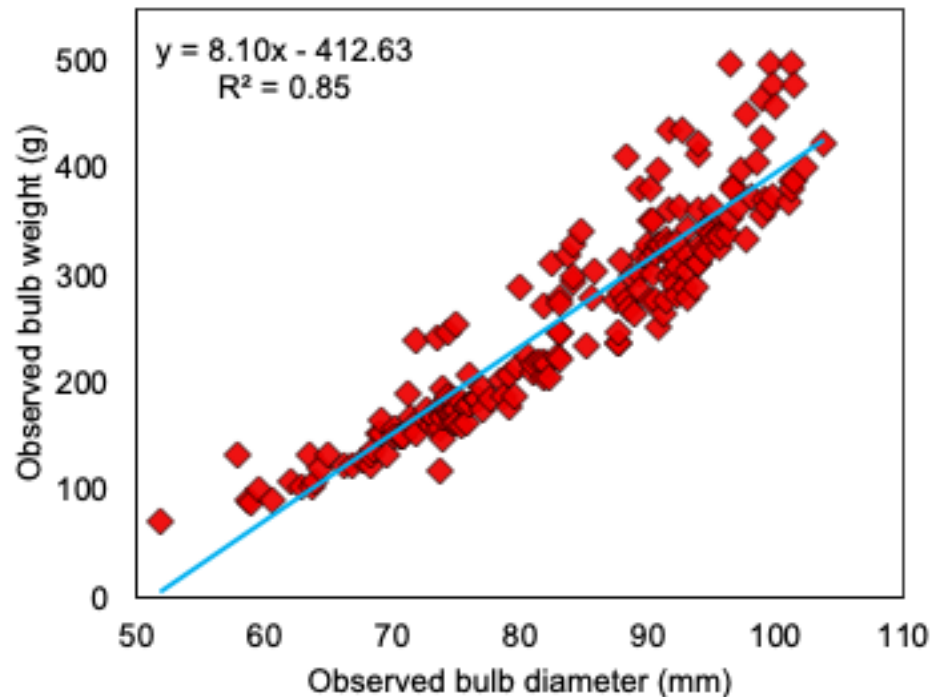
> 97%

### Plant height

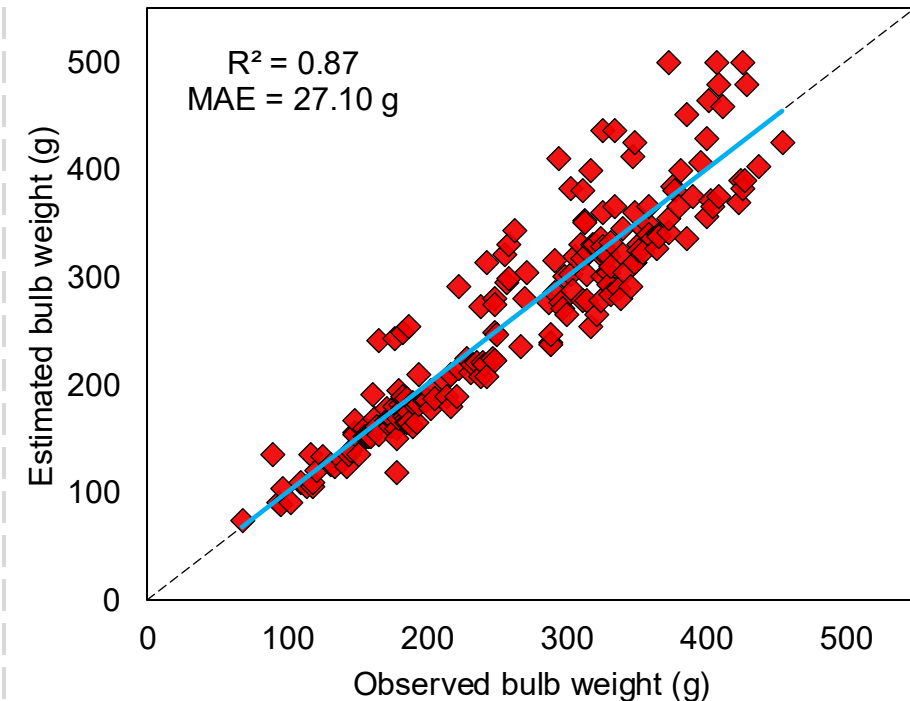


## Automated Crop Measurements with UAVs: An AI-Driven Platform for Counting and Biometric Analysis

Bulb diameter vs Bulb weight



Bulb weight: Observed vs Estimated





# Integrating Cutting-Edge Technologies for Crop Monitoring and Management



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## Automated Crop Measurements with UAVs: An AI-Driven Platform for Counting and Biometric Analysis

BACK TO ANALYSIS **Plant AI**

PROVIDE EXAMPLES

ANALYZE WHOLE FIELD

REVIEW RESULTS

When you are satisfied with the results, select the result and click "Proceed to Analysis".

Latest detection • 19,952 Plants

Show detected rows

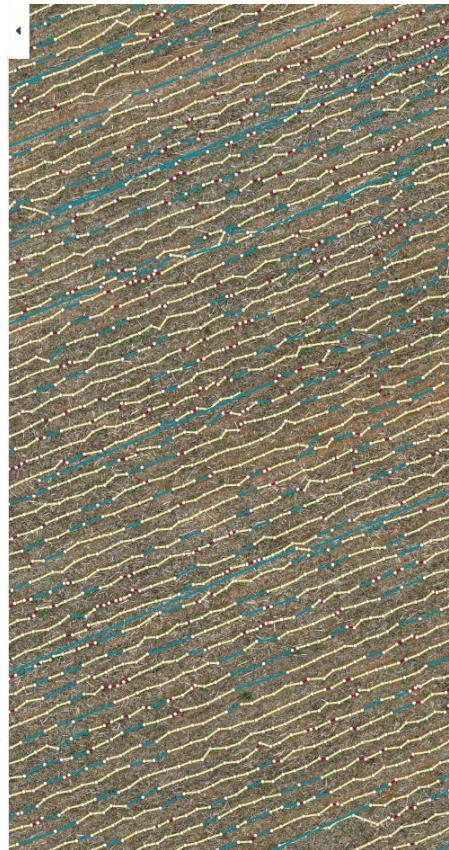
PROCEED TO ANALYSIS

NEED TO IMPROVE?

If some of the plants were missed or detected mistakenly, click "Provide More Examples" to add examples in areas that need improvement and repeat the workflow.

PROVIDE MORE EXAMPLES

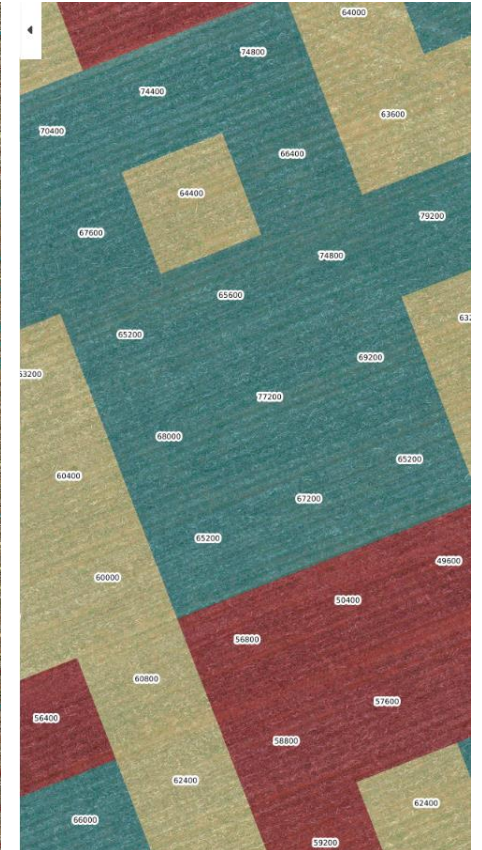
Plant distance



Plant diameter



Plant population



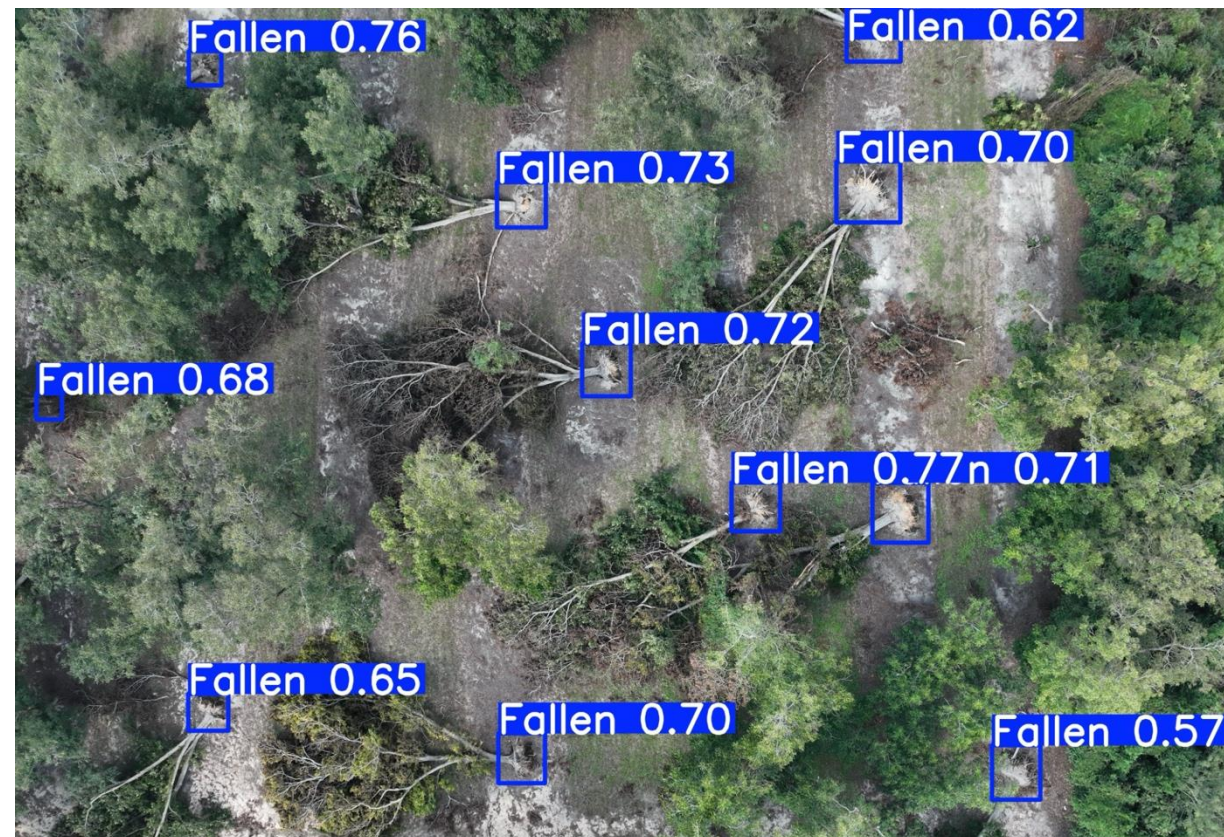


## Monitoring Hurricane Effects in Pecan Fields: An Object Detection Framework to Detect Fallen Trees

Pecan trees affected by Hurricane Helene



Automatic fallen tree identification (Drone and AI)





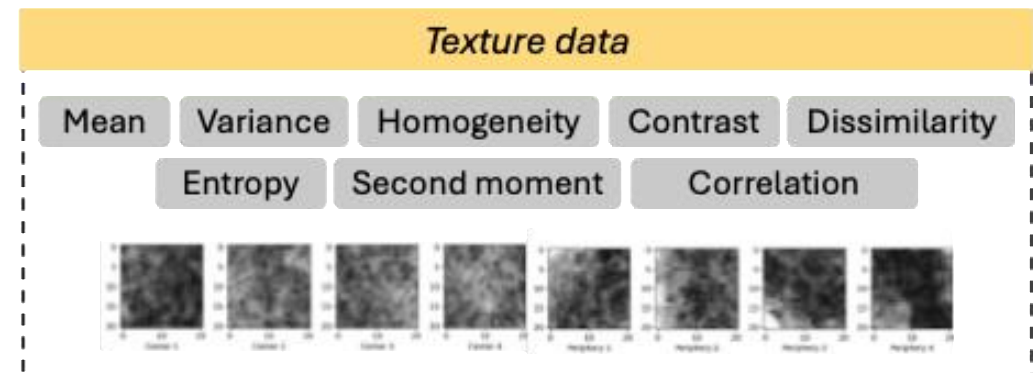
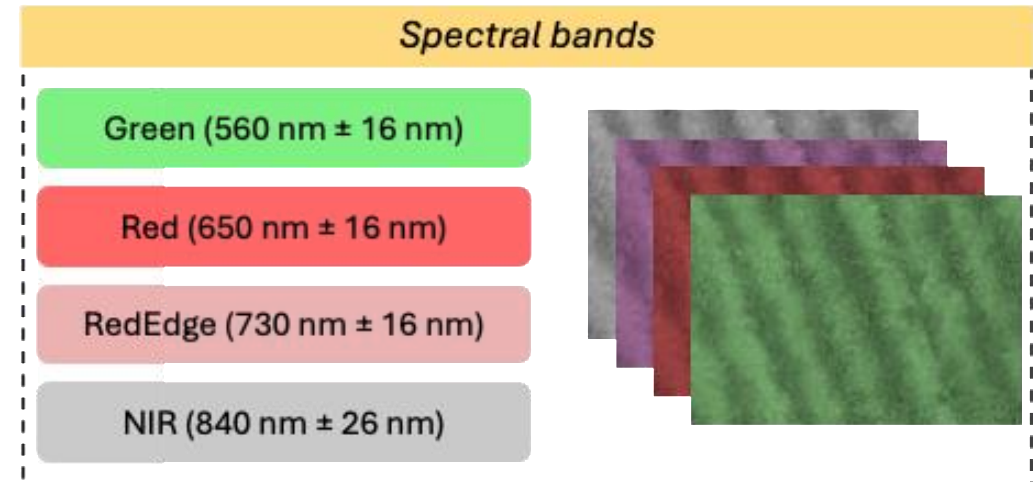
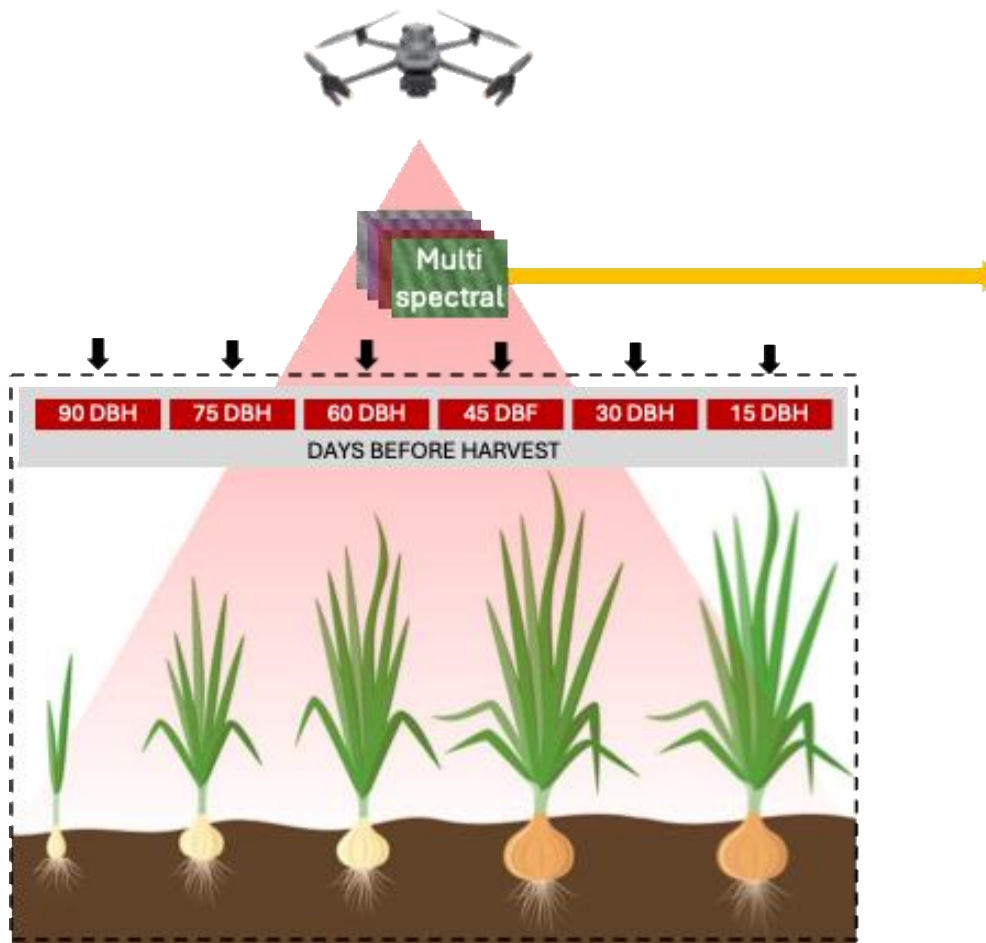
# Integrating Cutting-Edge Technologies for Crop Monitoring and Management



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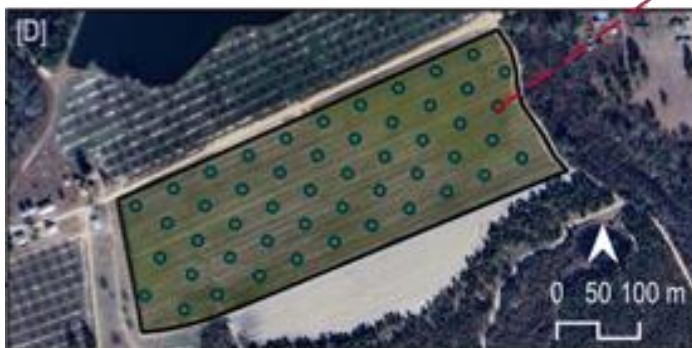


## Forecasting yield and market classes of Vidalia sweet onions: A UAV-based multispectral and texture data-driven approach





## Forecasting yield and market classes of Vidalia sweet onions: A UAV-based multispectral and texture data-driven approach



**Field 1 [C] and Field 2 [D]**

Sample plots: 50 in each field

Plot dimension: 5 x 5 m

Harvest date: April 22 and 30, 2024

Measurements: Weight and Size

**Outputs: Yield and Market class**

**Medium** (~3 inches wide | 7.6 cm)

**Jumbo** (~3.75 inches wide | 9.5 cm)

**Colossal** (~4.25 inches wide | 10.8 cm)



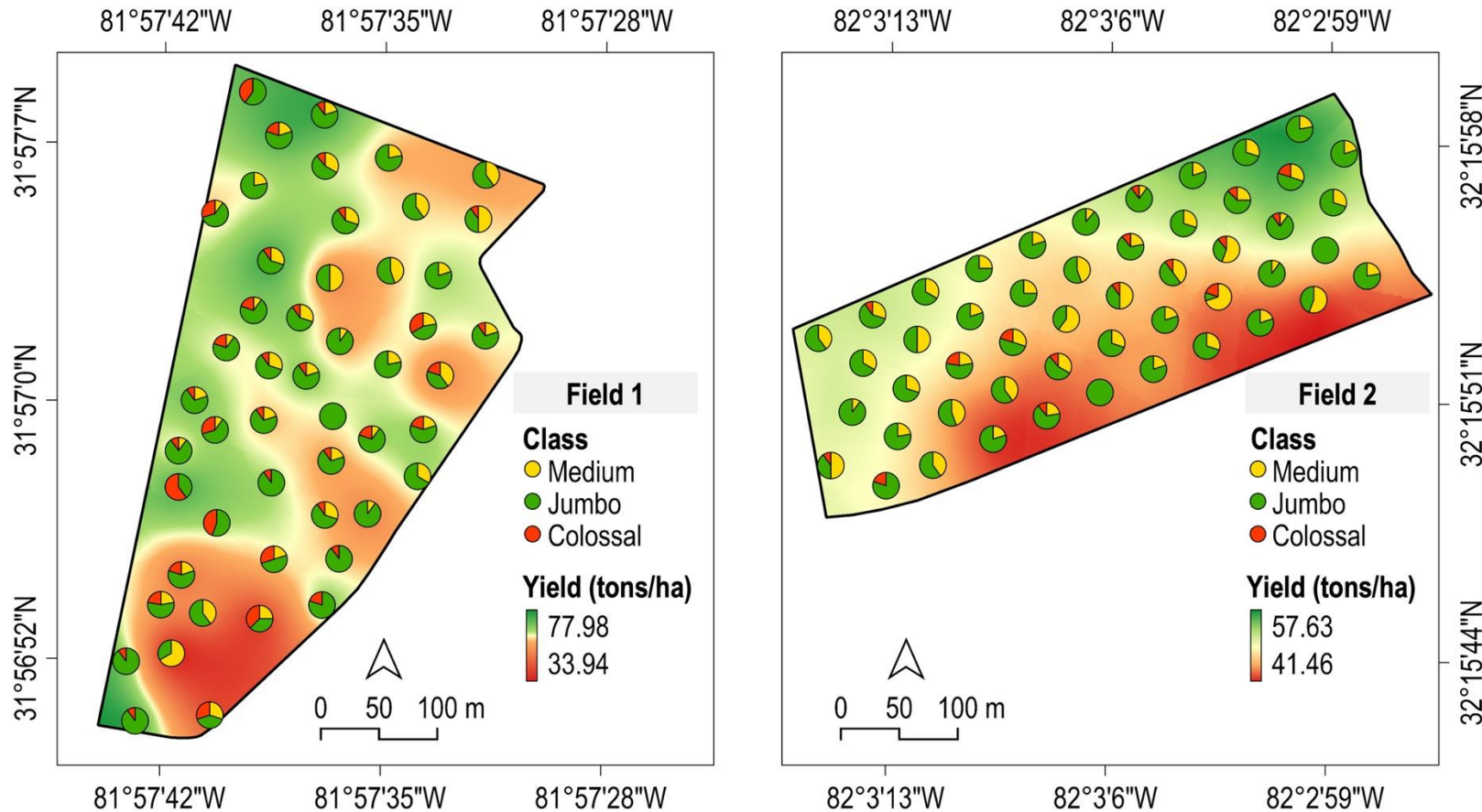
# Integrating Cutting-Edge Technologies for Crop Monitoring and Management



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## Forecasting yield and market classes of Vidalia sweet onions: A UAV-based multispectral and texture data-driven approach



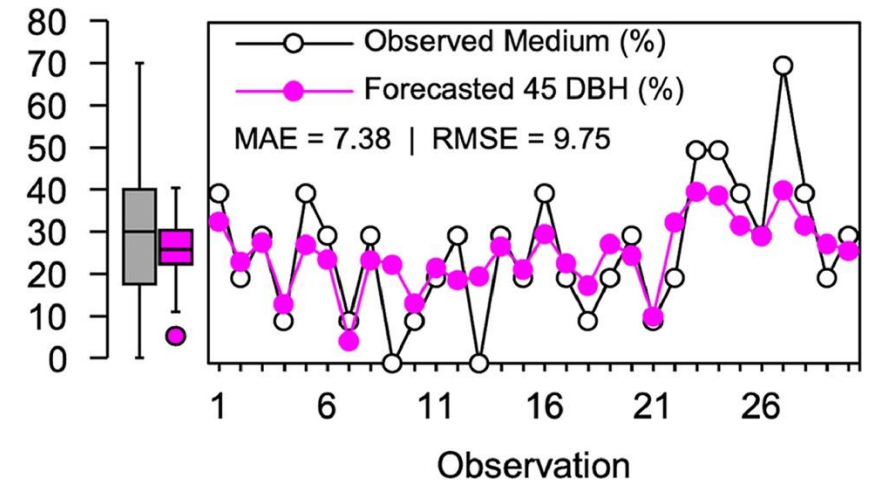
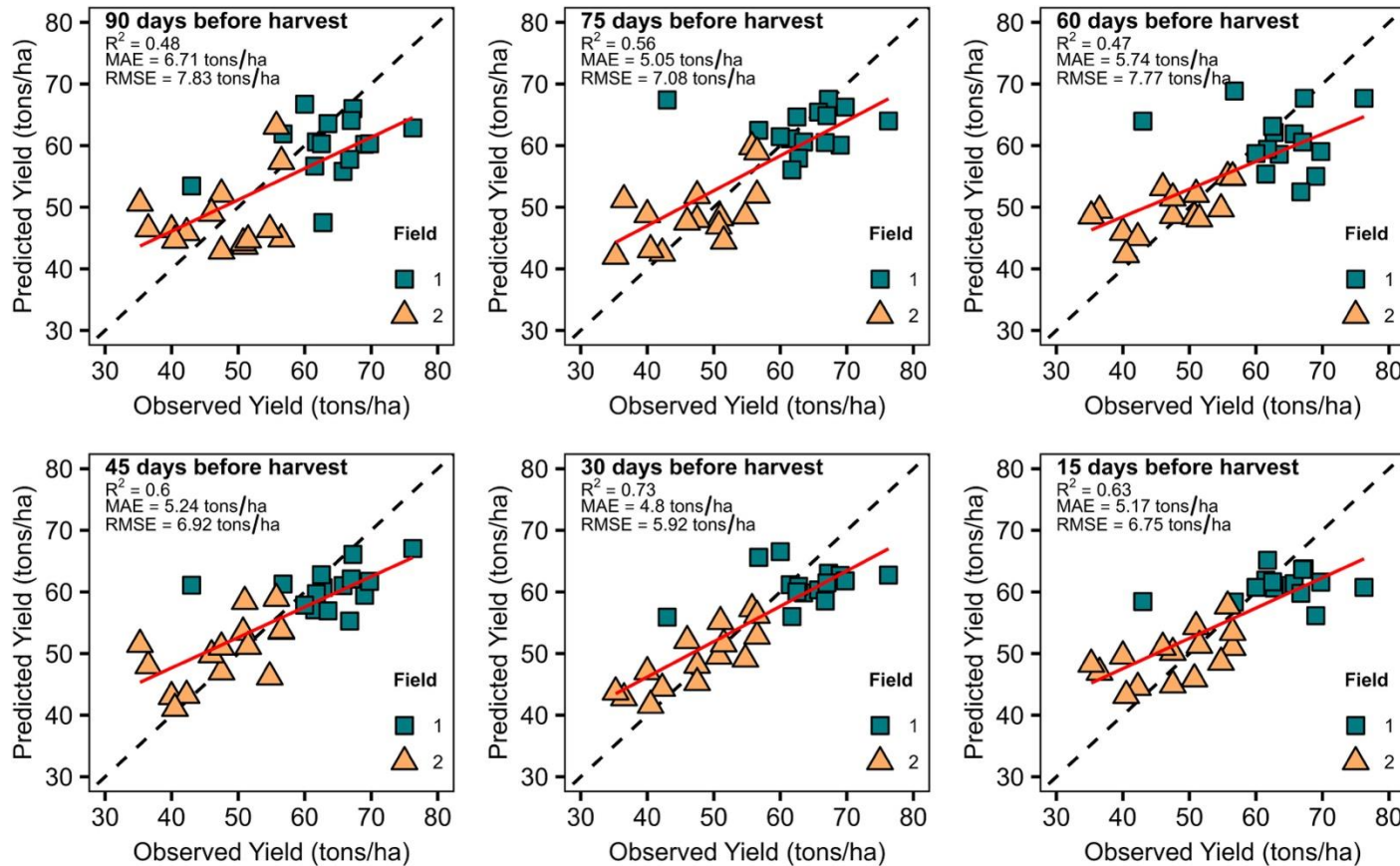
# Integrating Cutting-Edge Technologies for Crop Monitoring and Management



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## Forecasting yield and market classes of Vidalia sweet onions: A UAV-based multispectral and texture data-driven approach



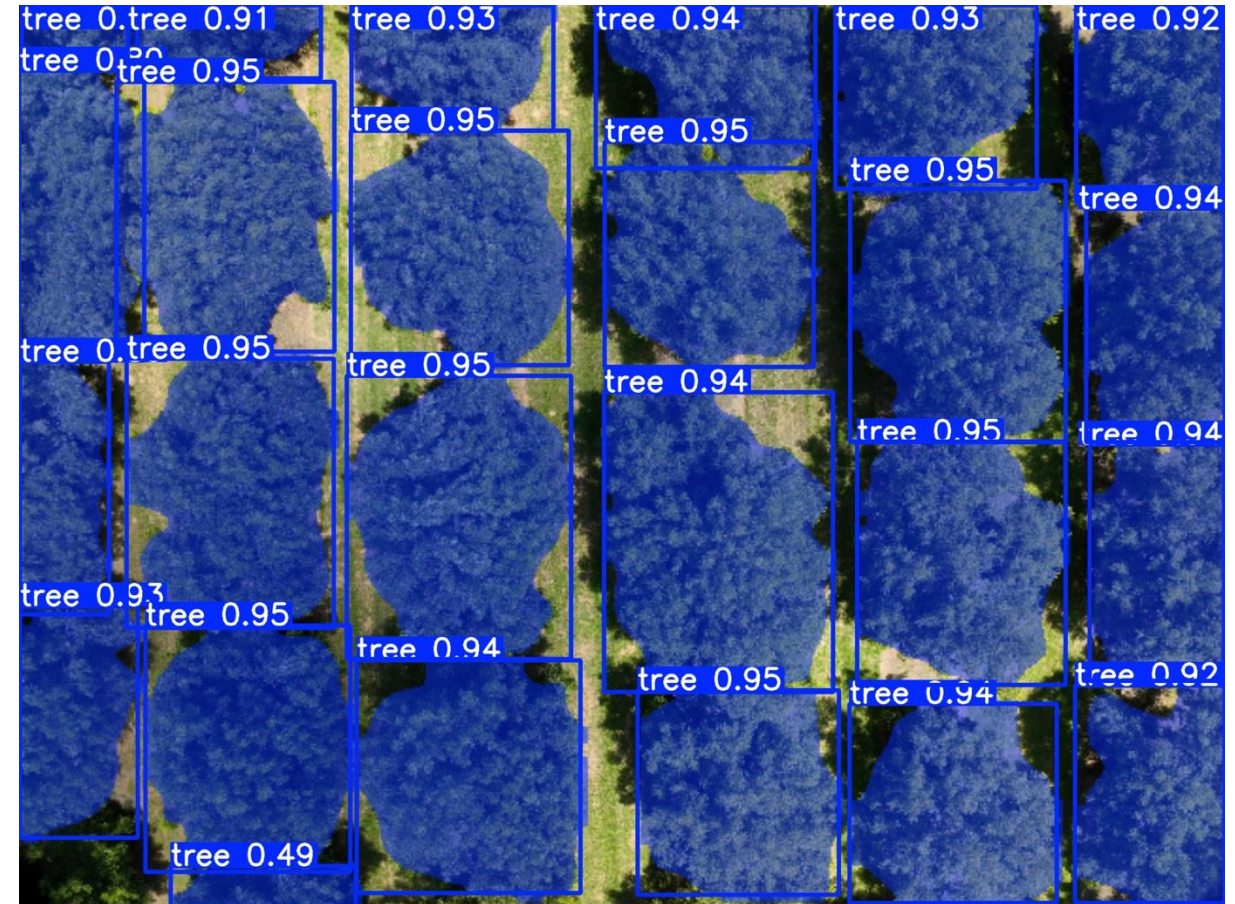
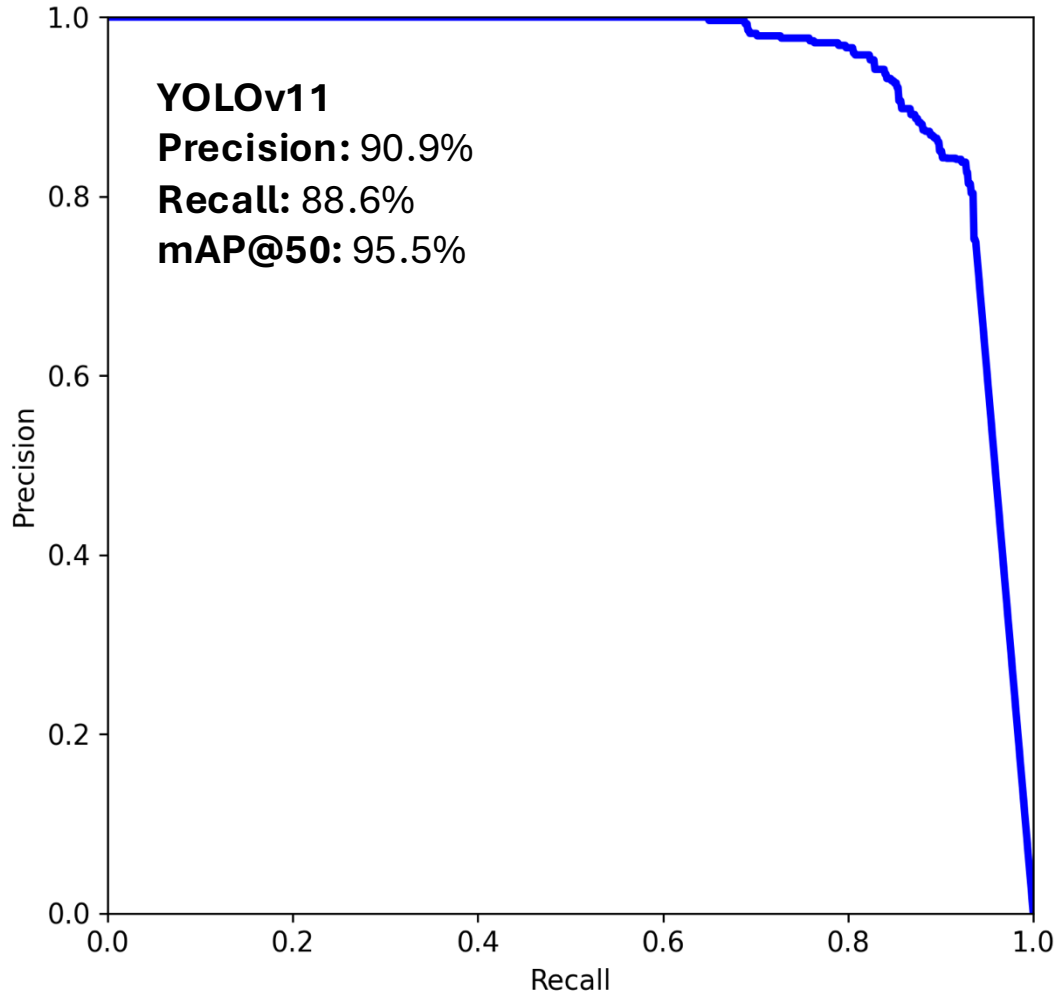


# Integrating Cutting-Edge Technologies for Crop Monitoring and Management



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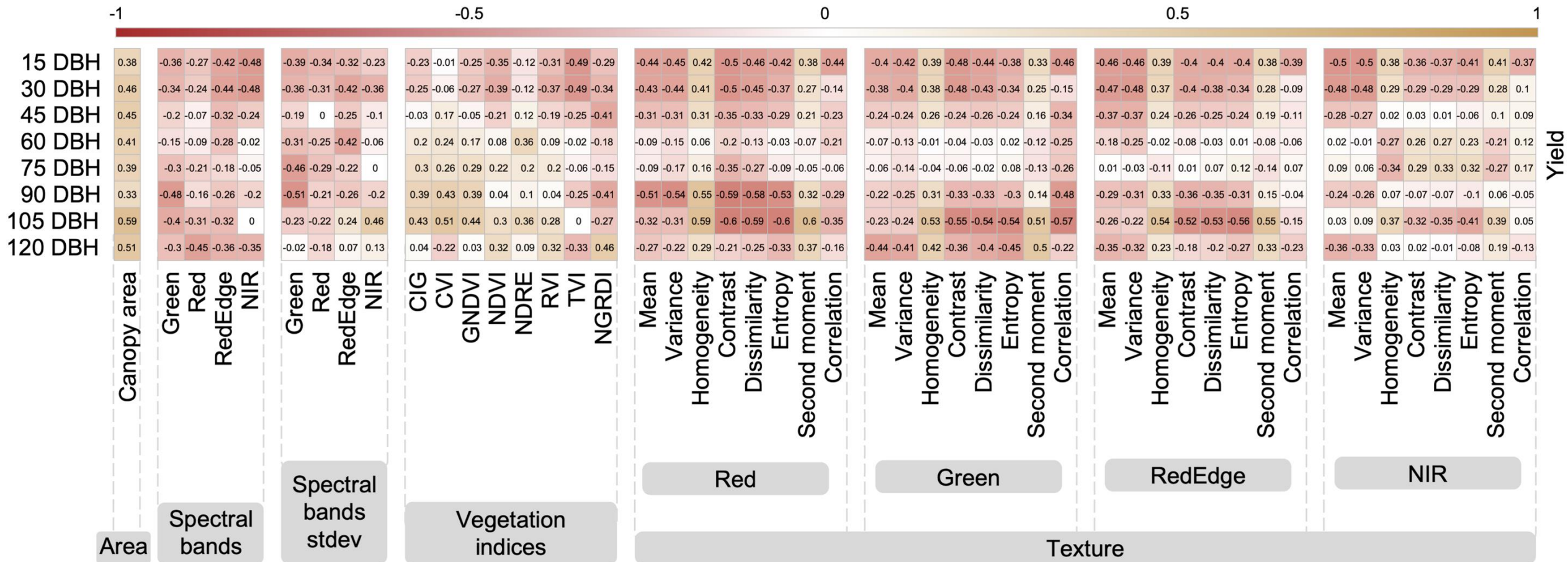
## AI-Driven Yield Forecasting Using UAV-Based Imagery: Insights from a Pecan Orchard



# Integrating Cutting-Edge Technologies for Crop Monitoring and Management



## AI-Driven Yield Forecasting Using UAV-Based Imagery: Insights from a Pecan Orchard



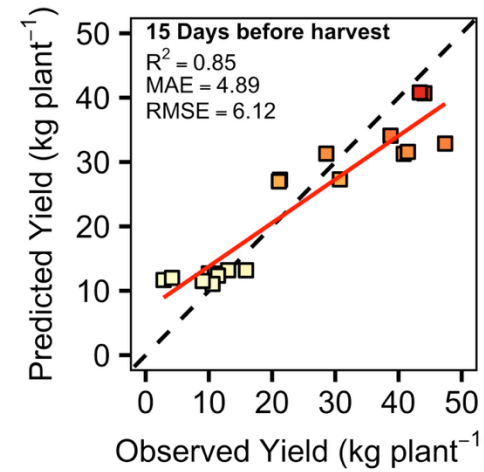
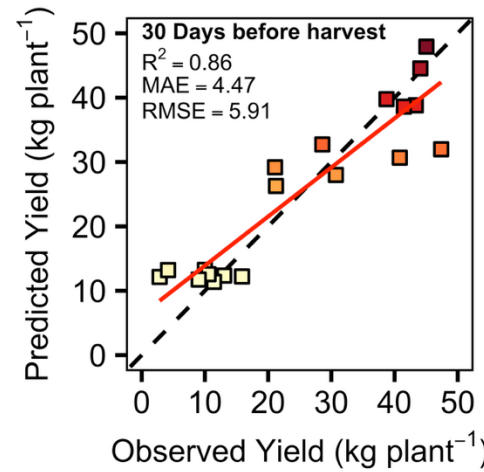
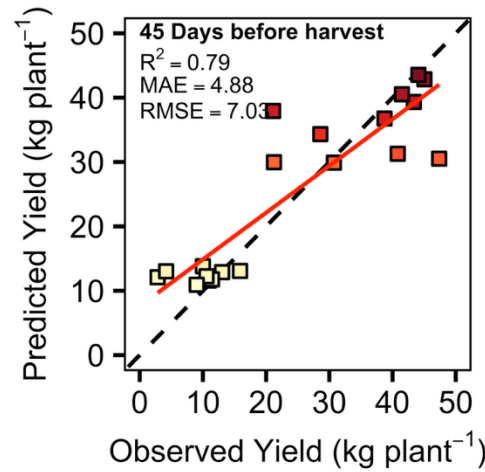
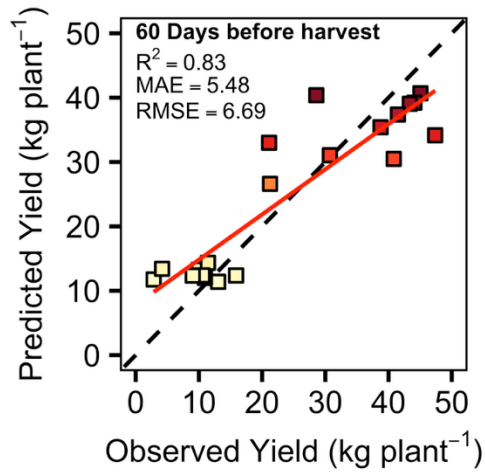
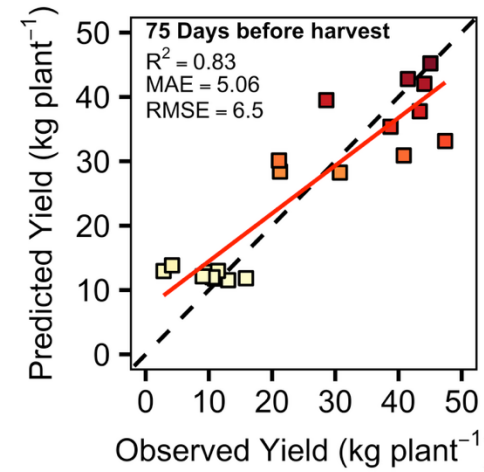
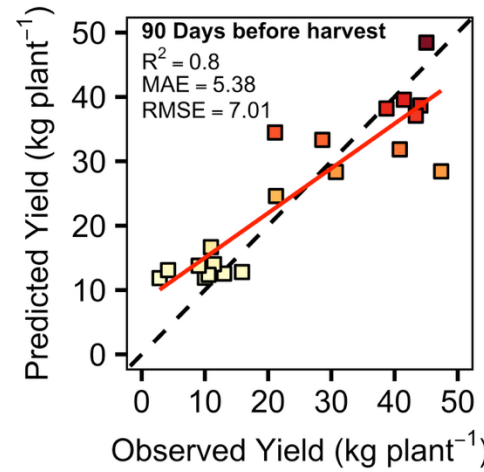
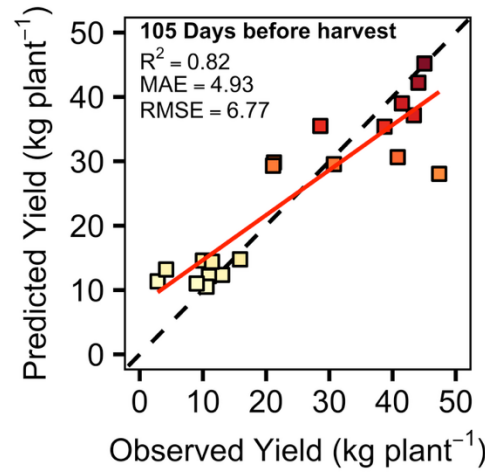
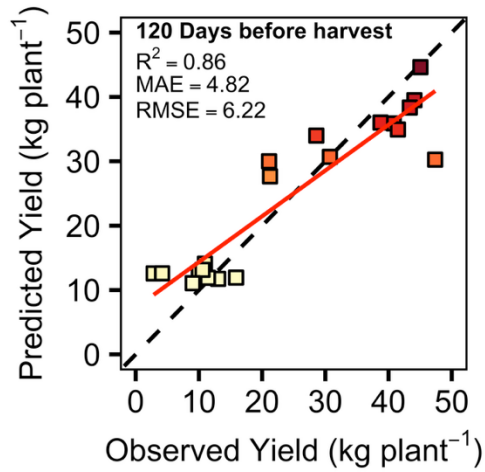


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## AI-Driven Yield Forecasting Using UAV-Based Imagery: Insights from a Pecan Orchard

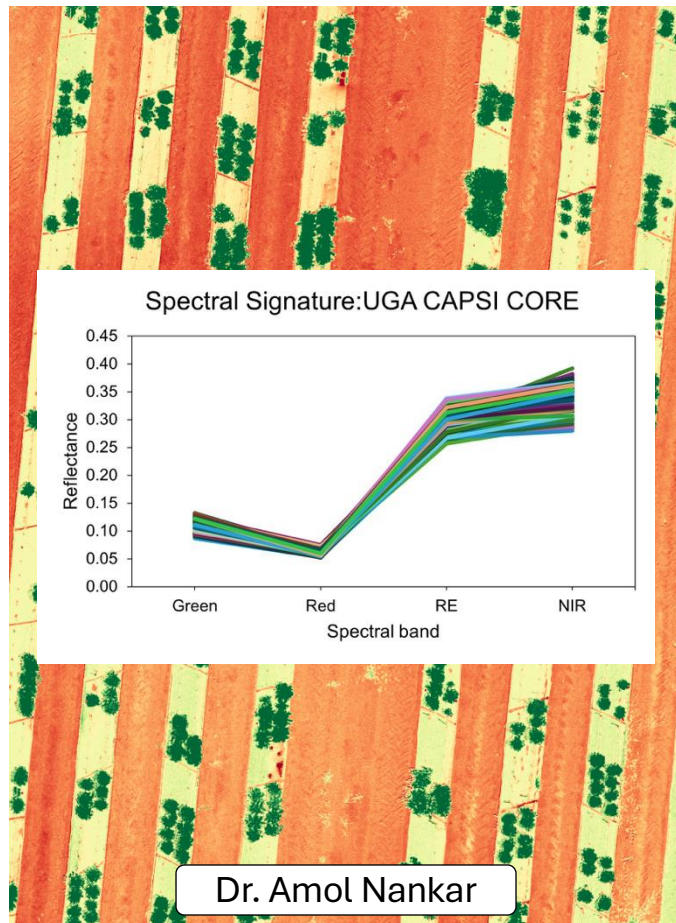


# Integrating Cutting-Edge Technologies for Crop Monitoring and Management



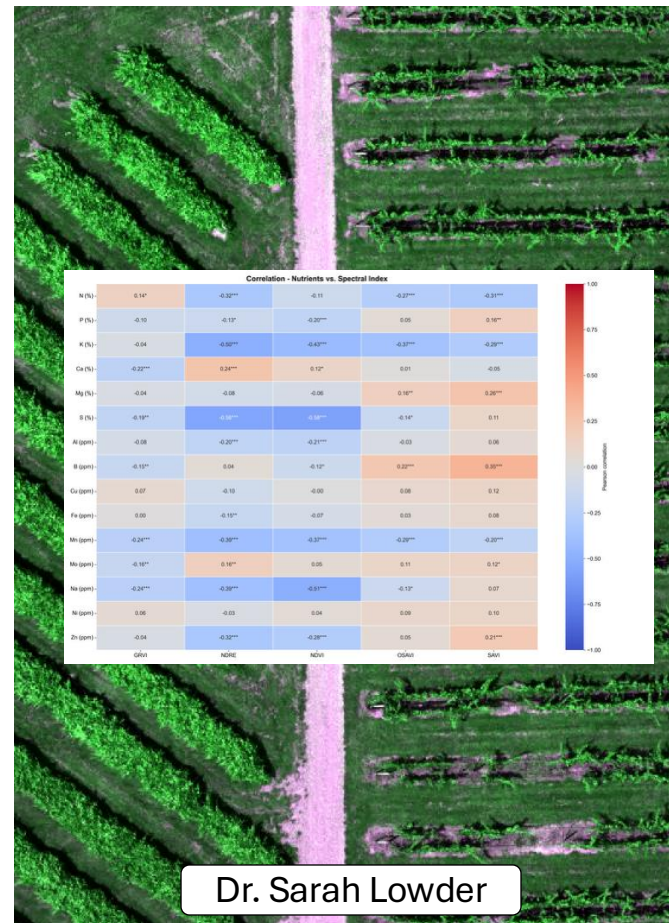
## Drone applications to support plant breeding and plant nutrition

Peppers (breeding)



Dr. Amol Nankar

Grape (nutrition)



Dr. Sarah Lowder

Pecan (nutrition-zinc)

Trait	r
VARI	0.098
GLI	0.009
TGI	0.245**
GRVI	0.469**
NDRE	0.119
NDVI	0.311**
SAVI	0.180**
OSAVI	0.242*

Dr. Patrick Conner



# Integrating Cutting-Edge Technologies for Crop Monitoring and Management



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Robot (mower)



Robot (spray – bar system)



Robot (spray - atomizer)



# Integrating Cutting-Edge Technologies for Crop Monitoring and Management



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## Atomizer – 25 GPA

Coverage (%)

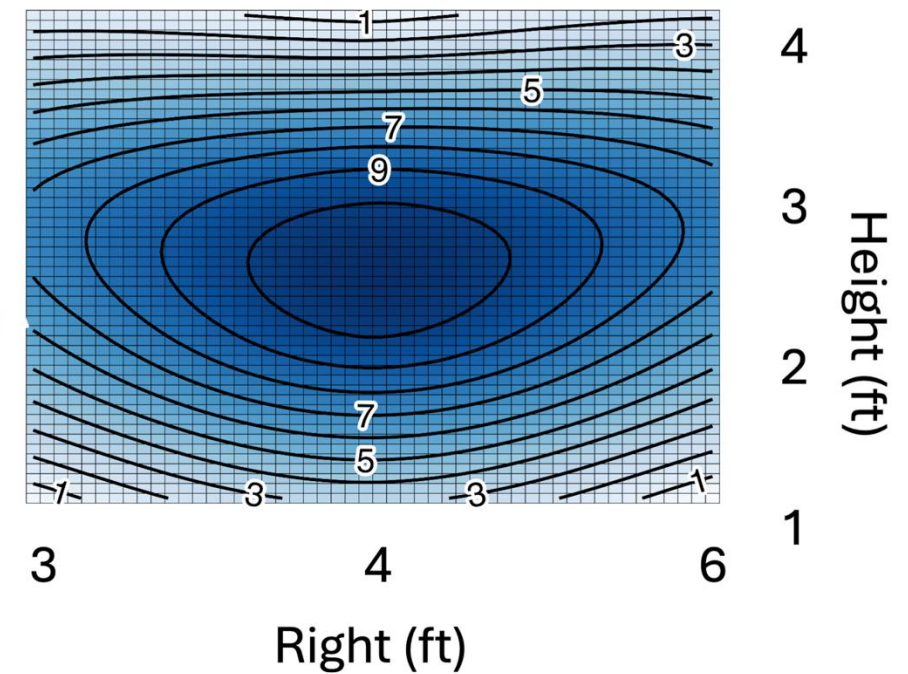
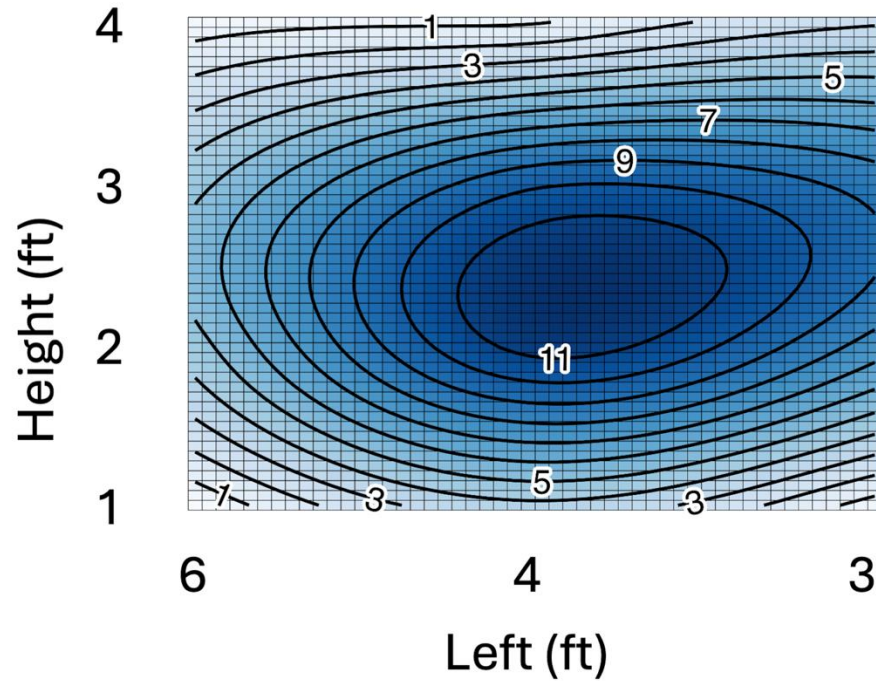


3 6 9

Coverage (%)



2.5 5.0 7.5 10.0

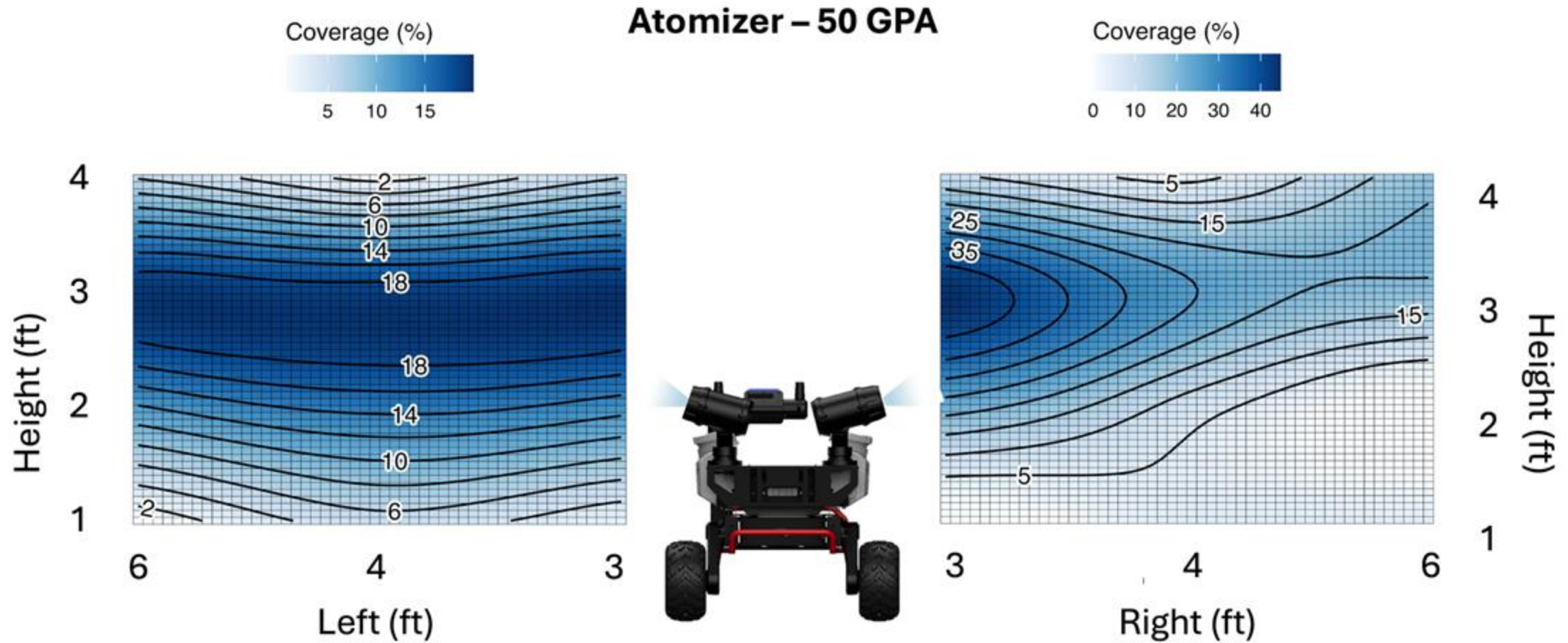




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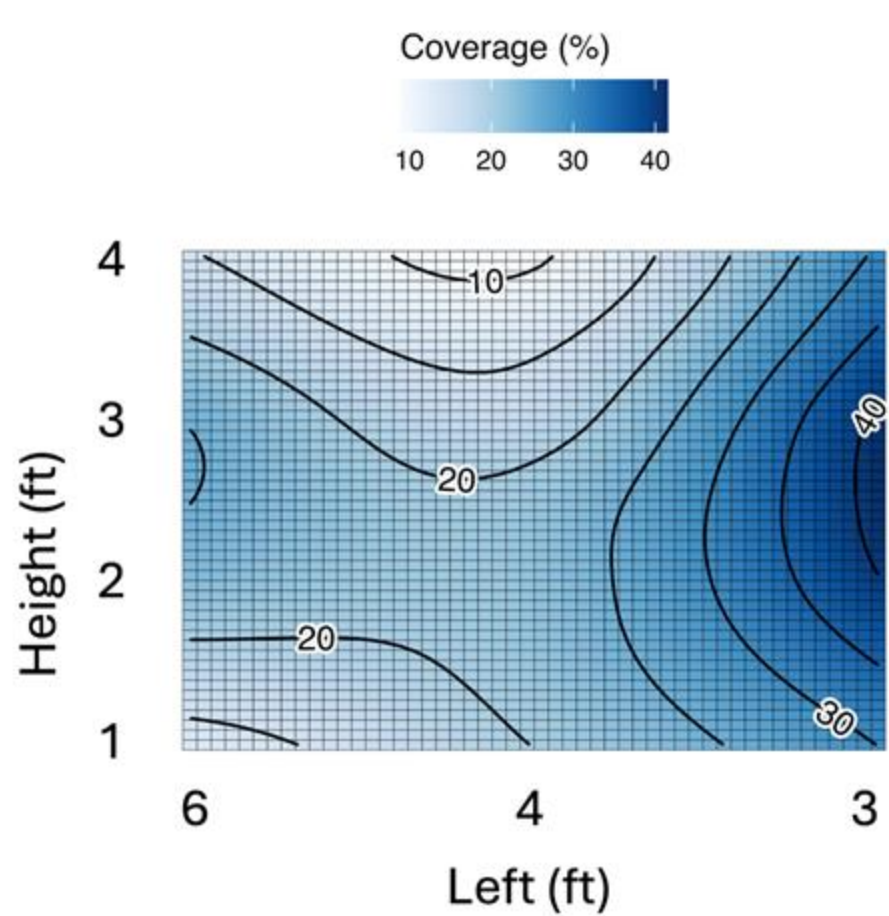


# Integrating Cutting-Edge Technologies for Crop Monitoring and Management

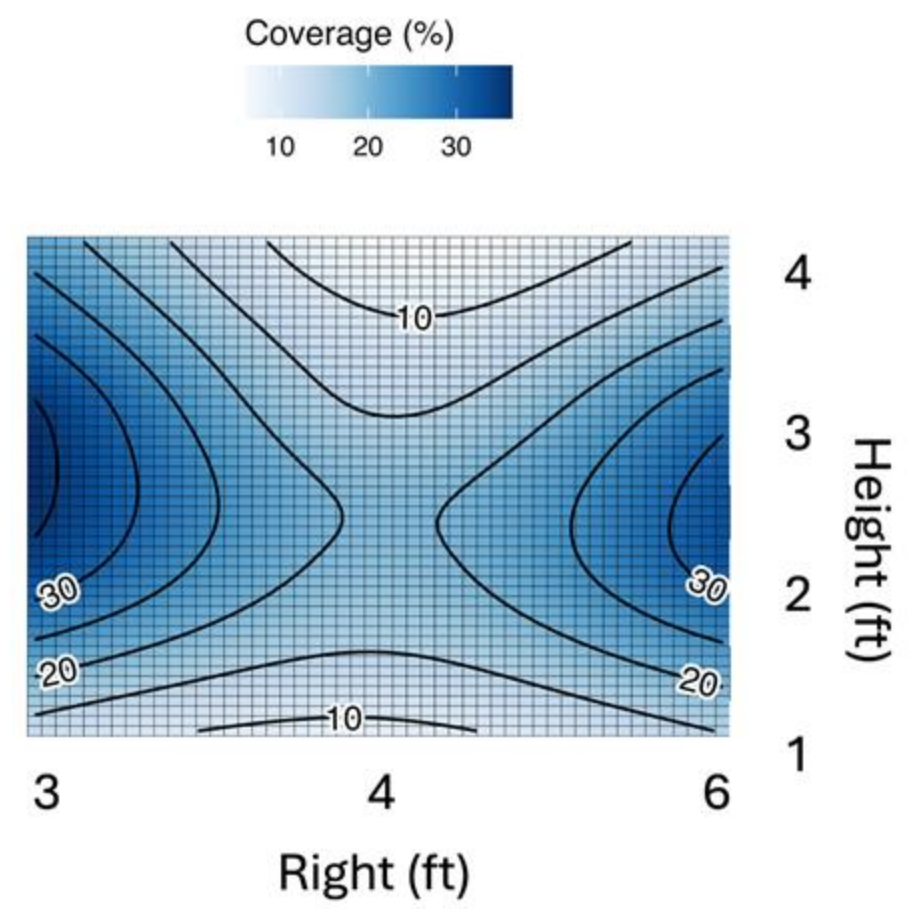


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**Bar – 25 GPA**

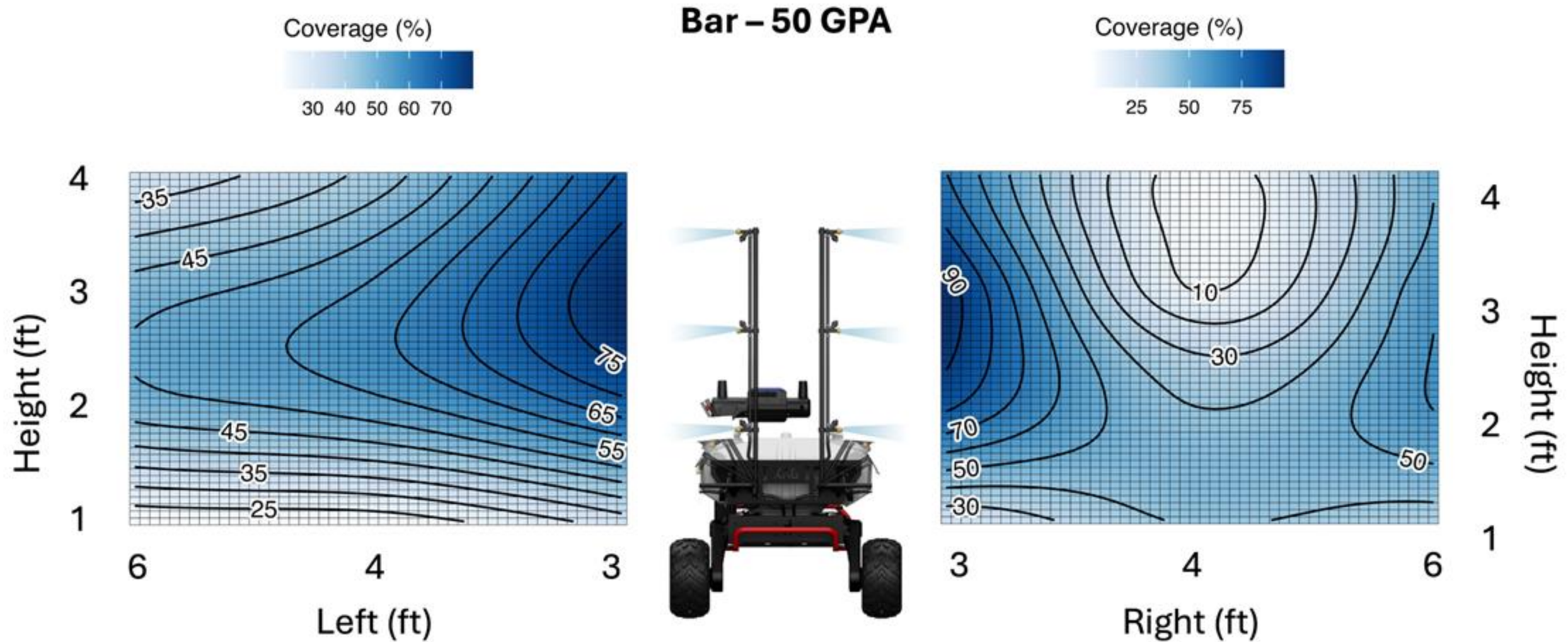




# Integrating Cutting-Edge Technologies for Crop Monitoring and Management



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# Integrating Cutting-Edge Technologies for Crop Monitoring and Management



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Robot (spot spray)





# Integrating Cutting-Edge Technologies for Crop Monitoring and Management

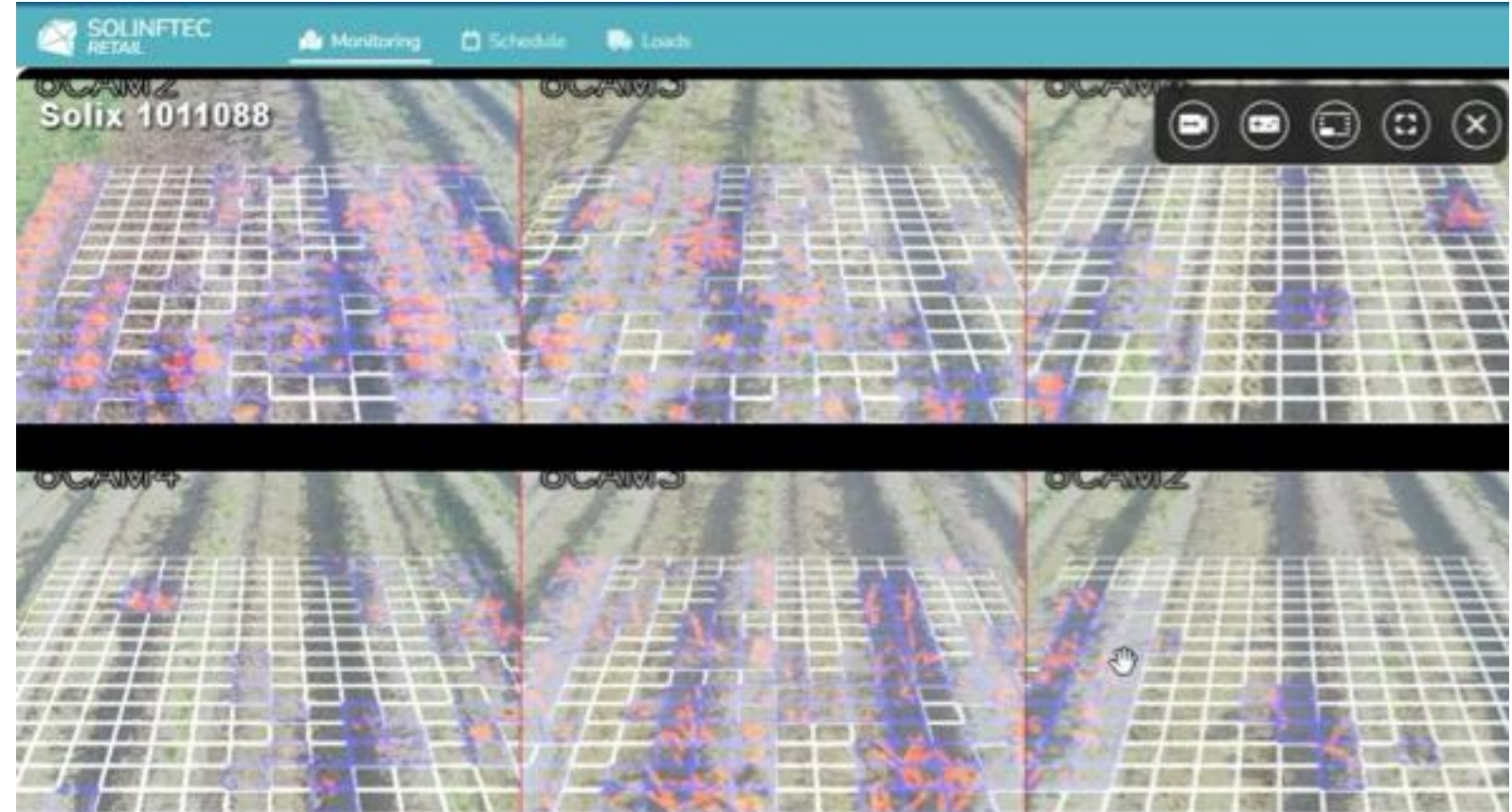


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Robot (spot spray)



Robot (vision system – data collection)





# Integrating Cutting-Edge Technologies for Crop Monitoring and Management



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## Designing and Implementing a Ground-Based Robotic System to Support Spraying Drone Operations: A Step Toward Collaborative Robotics





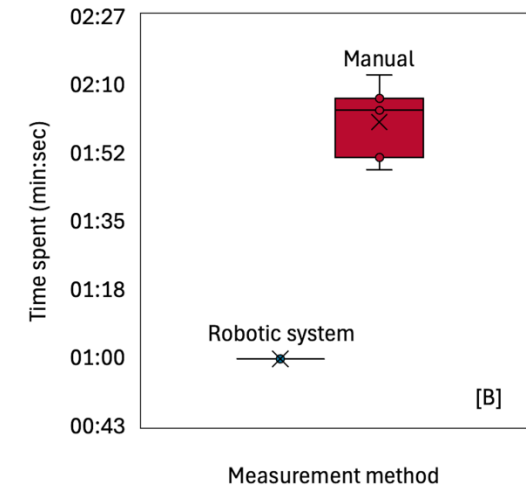
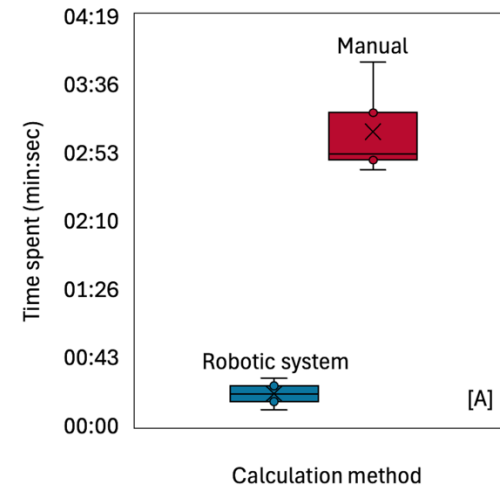
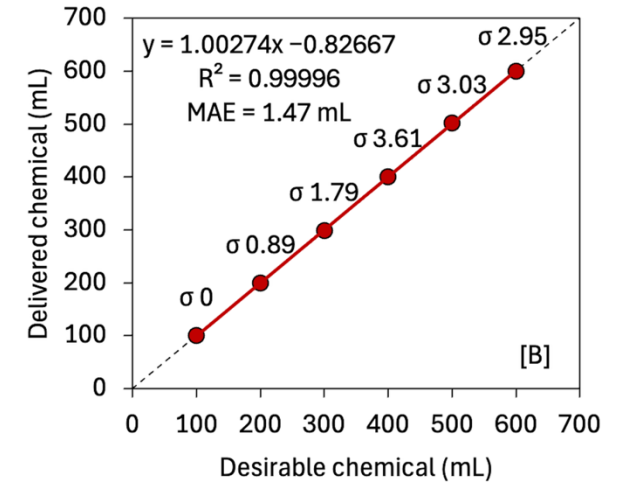
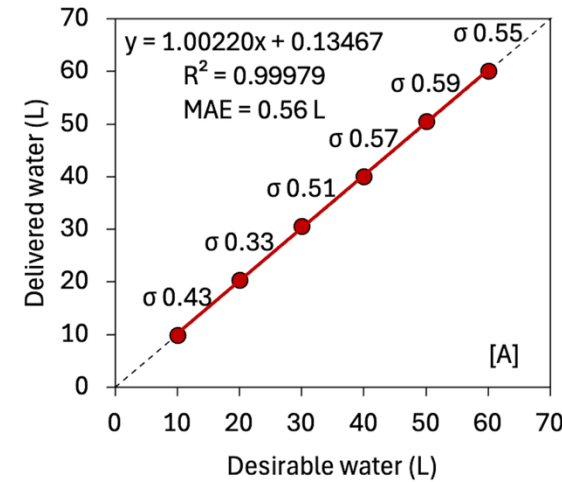
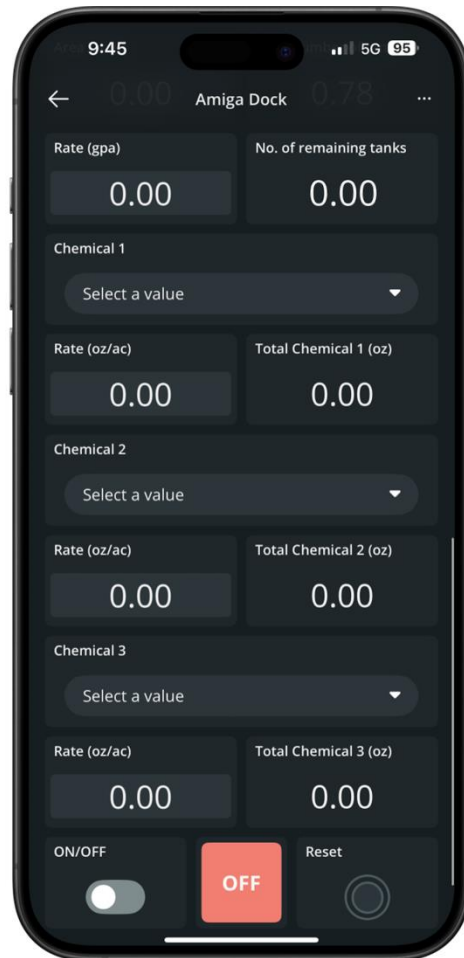
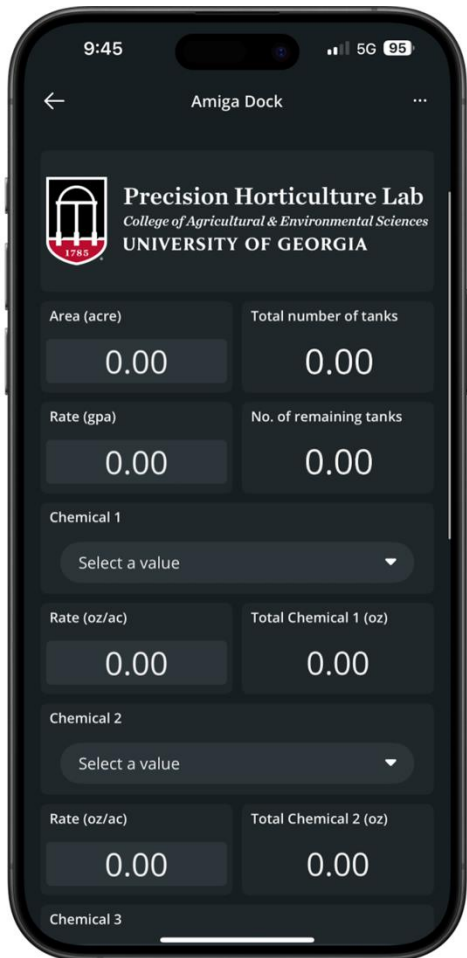
# Integrating Cutting-Edge Technologies for Crop Monitoring and Management



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## Designing and Implementing a Ground-Based Robotic System to Support Spraying Drone Operations: A Step Toward Collaborative Robotics



# Integrating Cutting-Edge Technologies for Crop Monitoring and Management



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## ARA Field Sprayer: AI-powered spot spray





# Integrating Cutting-Edge Technologies for Crop Monitoring and Management



**CROP MANAGEMENT  
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## Microwave system mounted on a robotic platform for nematode control



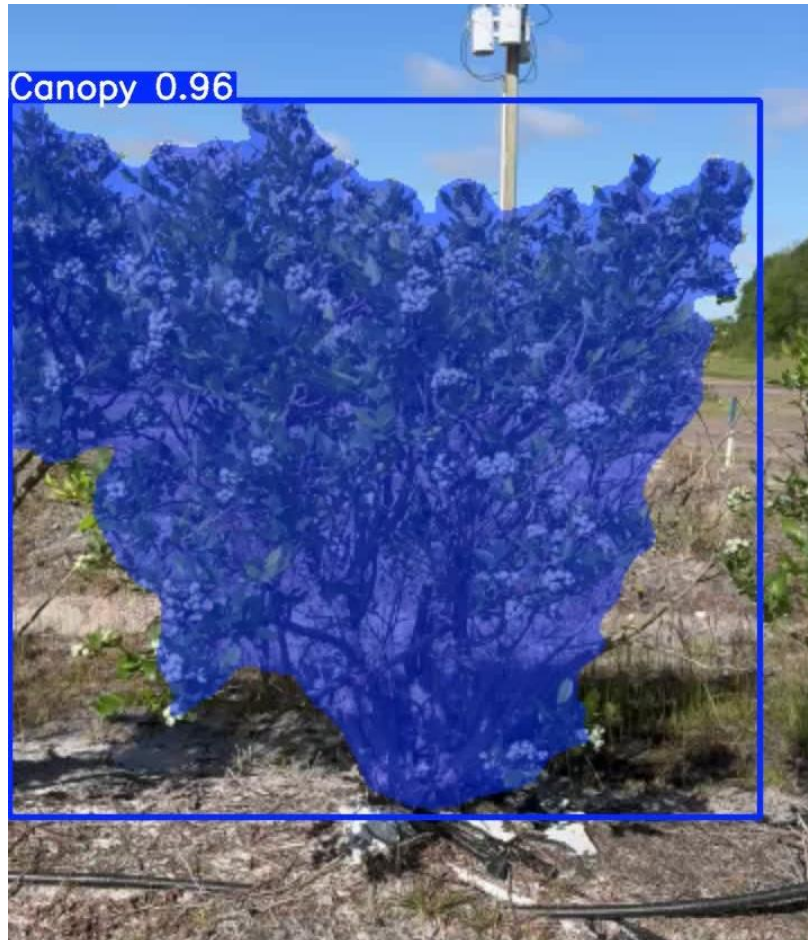


# Integrating Cutting-Edge Technologies for Crop Monitoring and Management



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## Blueberry plant and fruit monitoring using machine vision and robotic system





# Integrating Cutting-Edge Technologies for Crop Monitoring and Management



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Spraying drone



Conventional spraying system

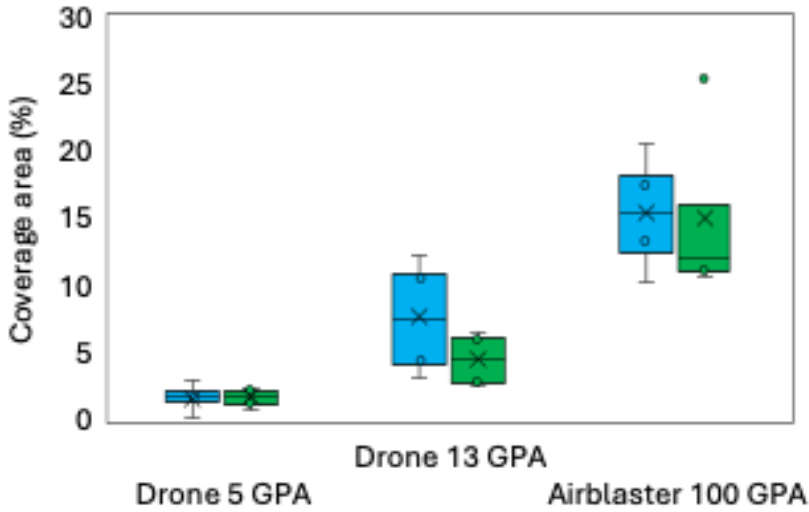


# Integrating Cutting-Edge Technologies for Crop Monitoring and Management

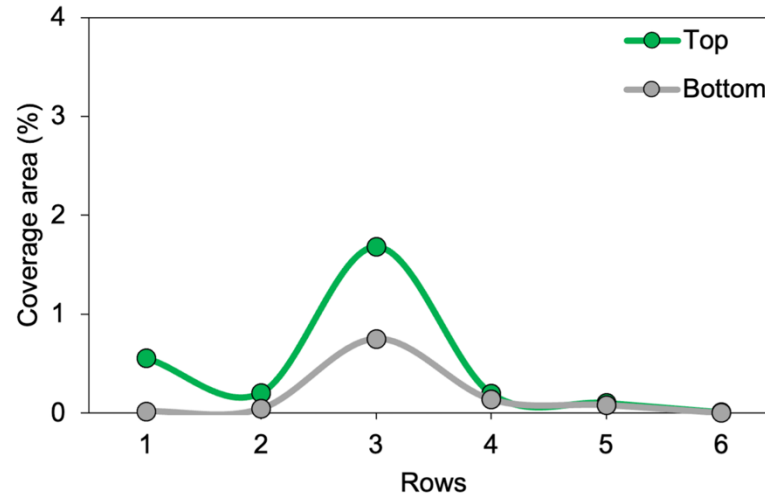


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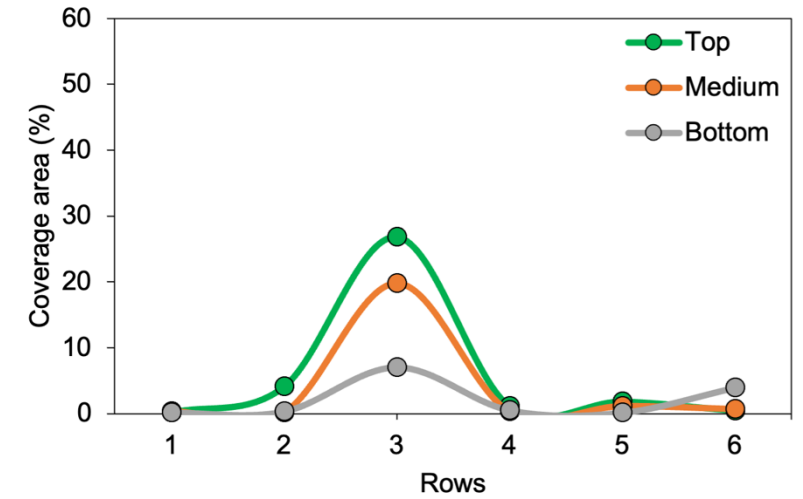
Pecan trees



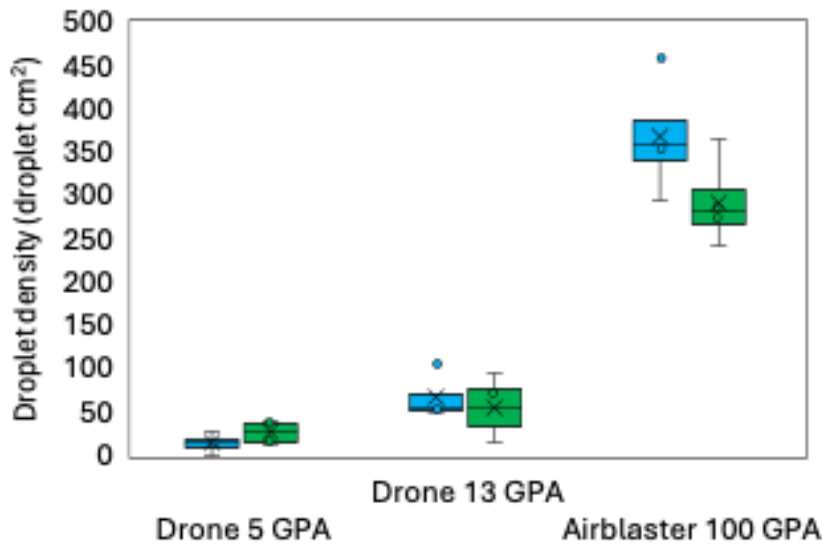
Bell pepper - Drone - 5 GPA



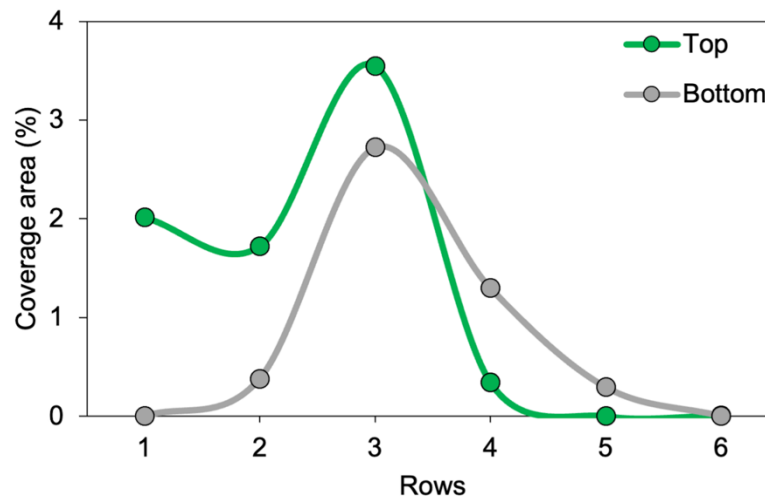
Cucumber - Drone - 5 GPA



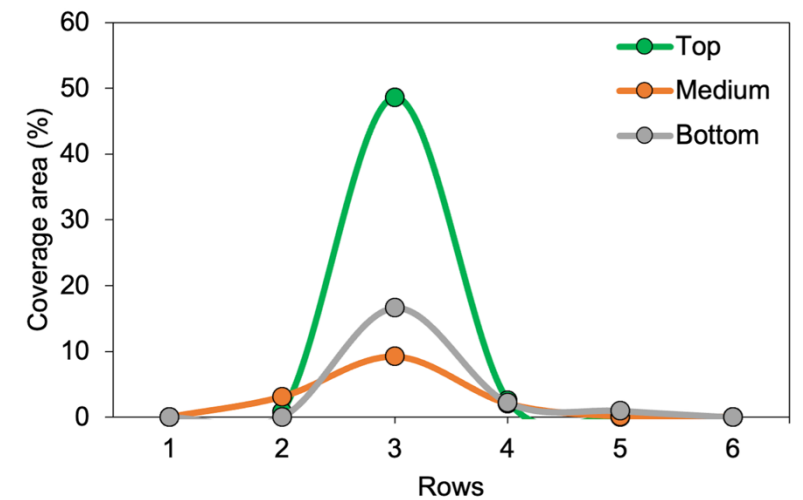
Young Mid-age



Bell pepper - Drone - 10 GPA



Cucumber - Drone - 10 GPA







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## Questions?

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